HITACHI INVERTER

SJ200/L200 Series

SERVICE MANUAL

(ADJUSTMENT AND MAINTENANCE)

Model: European Version SJ200/L200-002NFE(F) to SJ200/L200-022NFE(F) SJ200/L200-004HFE(F) to SJ200/L200-075HFE(F)

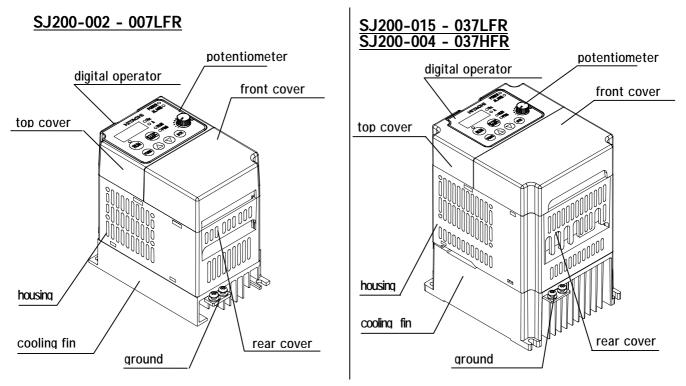
US Version

SJ200/L200-002NFU to SJ200/L200-022NFU SJ200/L200-037LFU to SJ200/L200-075LFU SJ200/L200-004HFU to SJ200/L200-075HFU



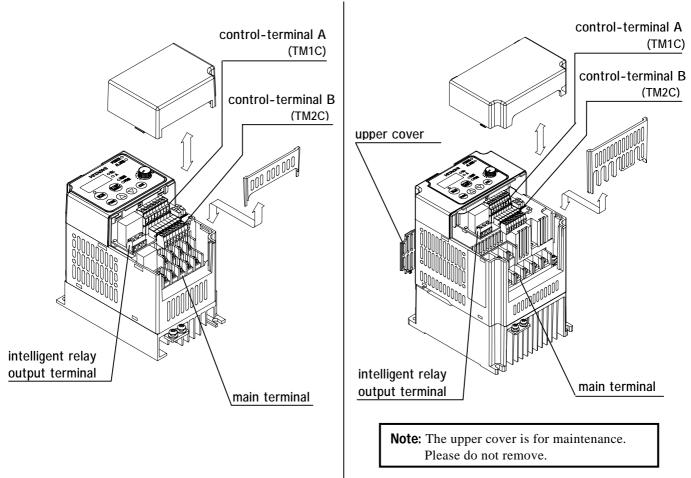
After reading this manual, keep it at hand for future reference

NBS650X

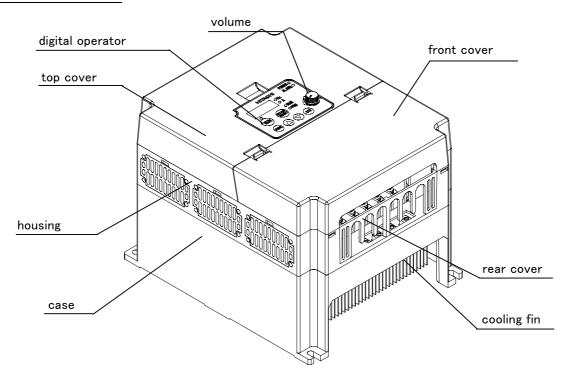


Appearance and name of each parts

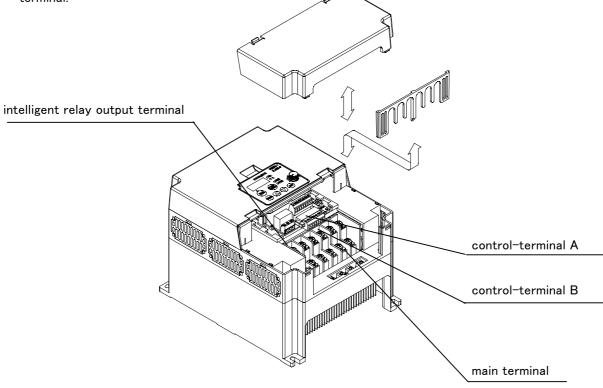
The front cover can be removed without any instruments. When you remove the front cover, you can set the mode switch and set wire at the control-terminal, the main-terminal and the intelligent relay output terminal.

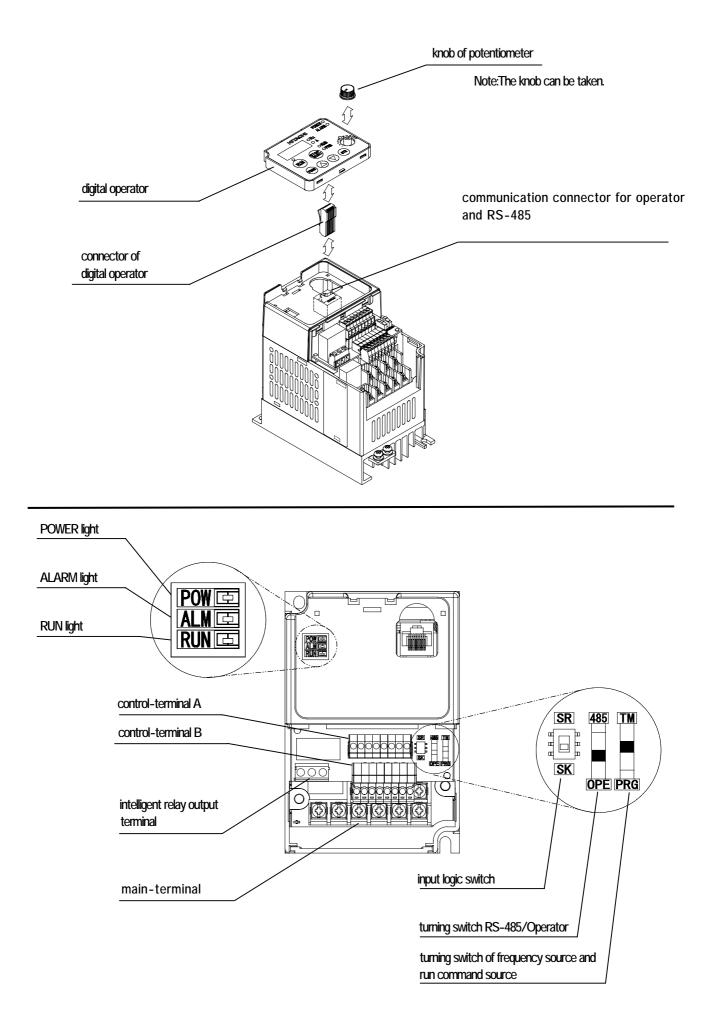


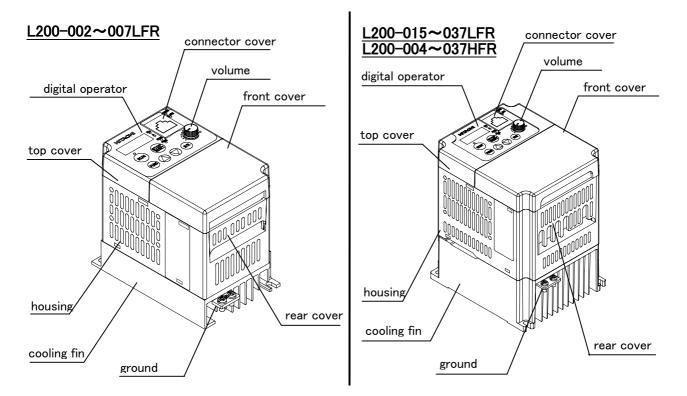
<u>SJ200-055~075LFR</u> SJ200-055~075HFR



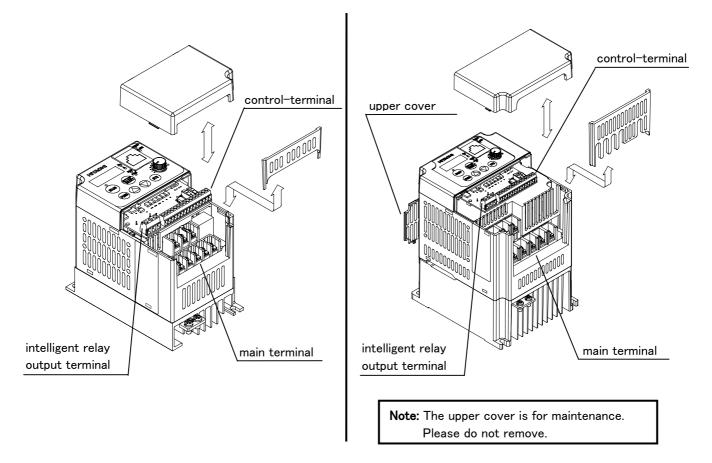
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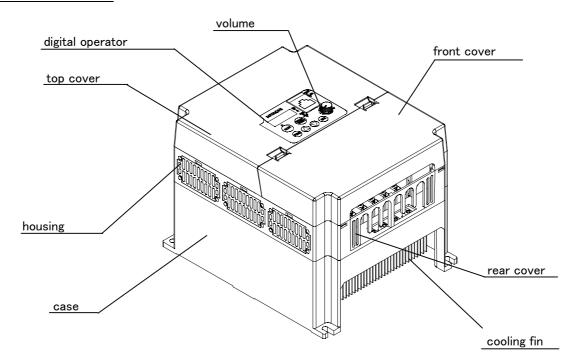




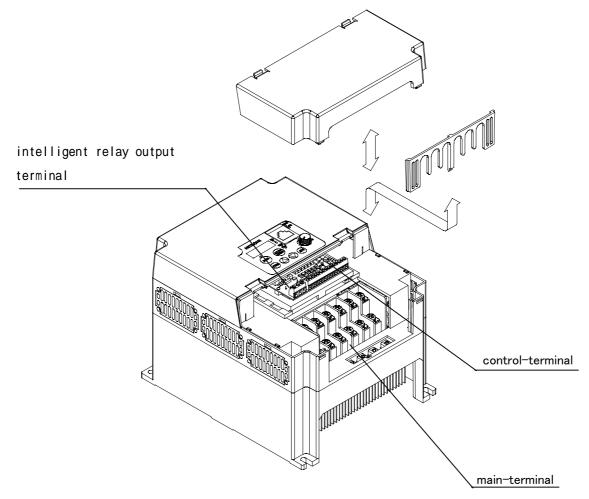
The front cover can be removed without any instruments. When you remove the front cover, you can set the mode switch and set wire at the control-terminal, the main-terminal and the intelligent relay, output terminal.



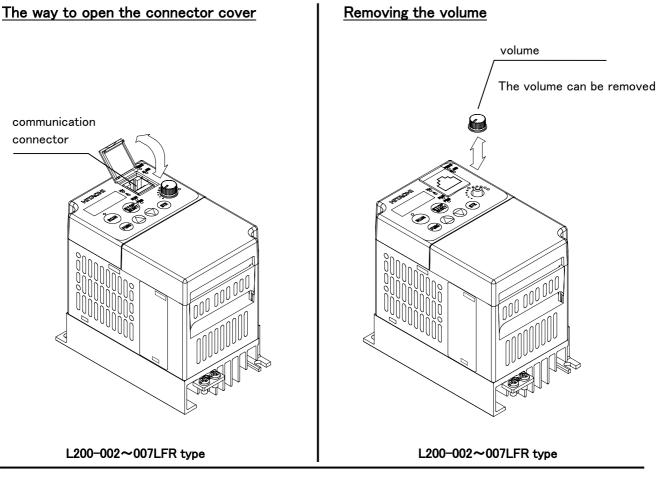
L200-055~075LFR L200-055~075HFR



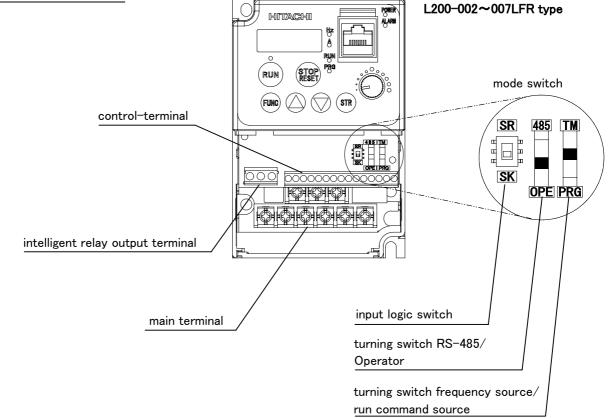
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(L200)

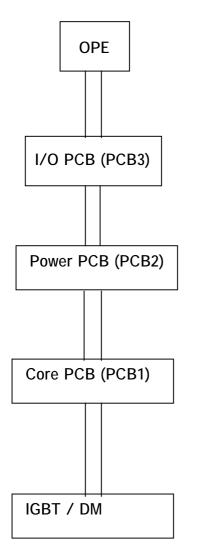


Items inside frontcover



Appearance

The appearance of SJ200 follows below.



OPE is a control unit. Formally OPE is attached to SJ200. But another OPE can be used optionally.

This part is a logic circuit. It has a microcomputer, which does calculation of the intelligent input, output, communication task and so on

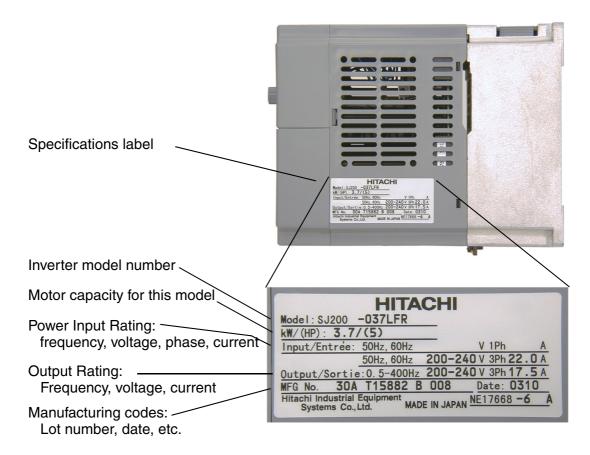
This part is a power circuit. It has a translator

This part is a core circuit. It has a microcomputer , which manages INV main function.

IGBT / DM. is a transistor unit for outputting to the motor. It depends on the capacity and the voltage class whether IGBT or DM is used.

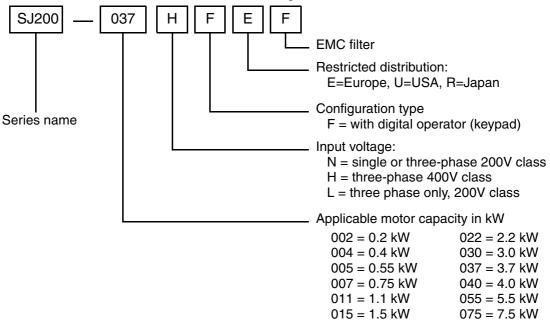
Inverter Specifications Label

The Hitachi SJ200 inverters have product labels located on the right side of the housing, as pictured below. Be sure to verify that the specifications on the labels match your power source, motor, and application safety requirements.



Model Number Convention

The model number for a specific inverter contains useful information about its operating characteristics. Refer to the model number legend below:



Orientation to Inverter Features

Unpacking and Inspection

Please take a few moments to unpack your new SJ200 inverter and perform these steps:

- 1. Look for any damage that may have occurred during shipping.
- 2. Verify the contents of the box include:
 - a. One SJ200 inverter
 - **b.** One Instruction Manual
 - c. One SJ200 Quick Reference Guide
- **3.** Inspect the specifications label on the side of the inverter. Make sure it matches the product part number you ordered.

Main Physical Features

The SJ200 Series inverters vary in size according to the current output rating and motor size for each model number. All feature the same basic keypad and connector interface for consistent ease of use. The inverter construction has a heat sink at the back of the housing. The larger models include a fan(s) to enhance heat sink performance. The mounting holes are predrilled in the heat sink for your convenience. Smaller models have two mounting holes, while larger ones have four. Be sure to use all the mounting holes provided.

Two chassis GND screws are located on the metal tab on the heat sink at the bottom of the inverter. Never touch the heat sink during or just after operation; it can be very hot.

The electronics housing and front panel are built onto the front of the heat sink.

Inverter Keypad - The inverter uses a digital operator interface, or keypad. The four-digit display can show a variety of performance parameters. LEDs indicate whether the display units are Hertz or Amperes. Other LEDs indicate Power (external), and Run/Stop Mode and Program/Monitor Mode status. Membrane keys Run and Stop/Reset, and an output frequency potentiometer (speed setting knob) control motor operation. The FUNC., \triangle , and $\forall \forall$ keys allow an operator to navigate to the inverter's functions and parameter values. The Store key is used when changing a setting.





*Keypad doesn't display when it is connected badly.

Inverter Keypad

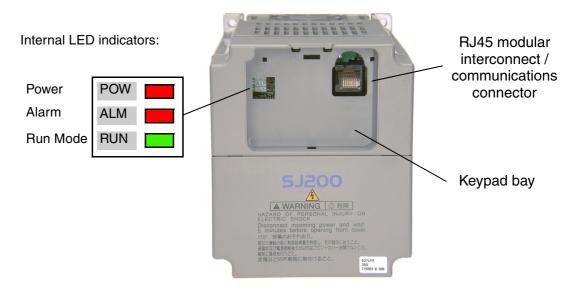
Keypad Removal - The SJ200 has a removable keypad. To remove the keypad, locate the retention latch as shown to the right. Press downward on the latch, while gently pulling toward you. The keypad will tilt forward, as two retaining tabs at the bottom edge of the keypad also hold it in place. Then remove the keypad from the keypad bay.

*Caution - Do not remove keypad when the power is on.



Internal LED Indicators / Communications Connector - Refer to the illustration below. After removing the keypad, the internal LED viewing window will be visible. These LEDs indicate status for your convenience when the keypad is remotely mounted and you are nearer to the inverter location.

The RJ45 connection consists of two parts. The clear plastic RJ45 modular interconnect makes the connection between the inverter and the keypad. It is easily removed to allow you to plug a communications cable into the modular connector.

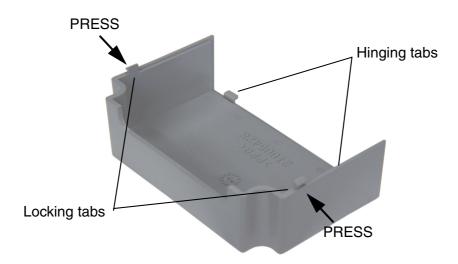


Installing the Keypad - Follow these steps:

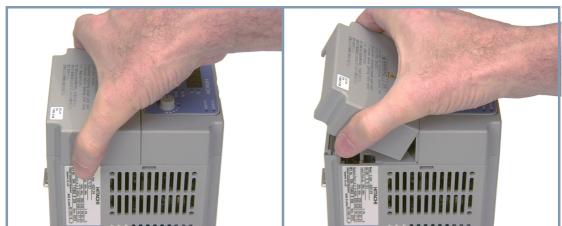
- **1.** Remember to install the RJ45 modular interconnect. Otherwise, there will be no connection to the keypad.
- 2. Set the bottom edge of the keypad into the inverter keypad bay.
- **3.** Tilt the top edge of the keypad forward. If it stops before seating firmly, DO NOT force the keypad. You may need to adjust the end RJ45 modular connector slightly (upward or downward). Then seat the keypad.
- **4.** Make sure the retention latch clicks into place on the inverter housing top edge. Otherwise, vibration may cause the keypad to loosen in the future.

Front Housing Cover

Housing Cover Removal - The front housing cover is held in place by two pairs of tabs. Since these are hidden from view, it is good to become familiar with their locations *before* attempting to remove the cover. The figure below shows a typical housing cover in upside-down position to reveal the tabs. The two locking tabs are the ones which you will need to press to remove the cover. The two hinging tabs will allow the cover to tilt open once the unlocking tabs are released.



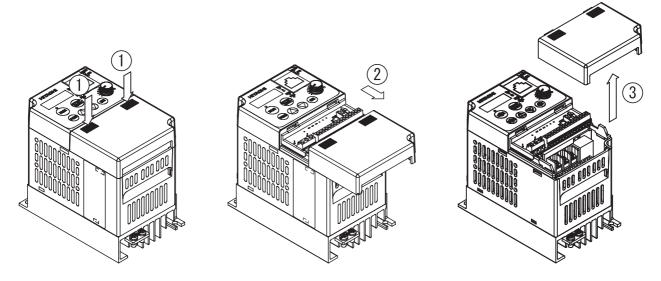
The figure below shows the procedure for removing the housing cover. While pressing inward on the housing, it is helpful to wiggle the cover side-to-side in order to release the locking tabs. DO NOT force the cover open; it is possible to break a tab in this way.



- 1. Press inward on both sides.
- 2. Tilt upward after both locking tabs are free.

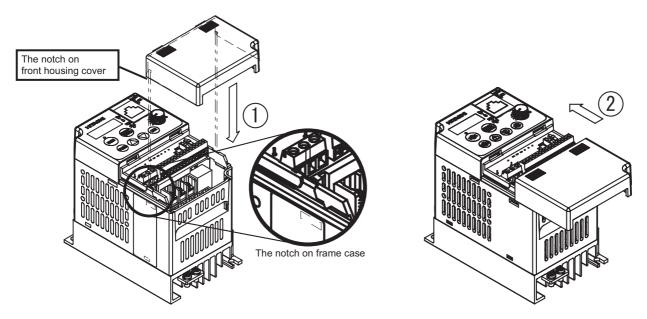
Removing the Cover (Slide type)

- 1. Press downward on the cover at the two areas indicated to release the retaining tabs.
- 2. Slide the cover forward and away from the keypad until the top edge of the cover reaches the notch in the inverter chassis.
- 3. Lift the cover upward to remove it.



Installing the Cover (Slide type)

- 1. Align the tabs on the front housing cover with the notch on each edge of the inverter chassis. Then lower the cover into position.
- 2. Slide the cover toward the keypad, keeping it flush against the inverter chassis. Continue until the cover latches into place.



Note: The example inverter in the diagrams is model L200-004LFU. The cover removal or installation method is the same for the other models.

WARNING: Be sure to turn off the power supply and wait 10 minutes before you remove the front housing cover. Otherwise, there is a shock hazard.

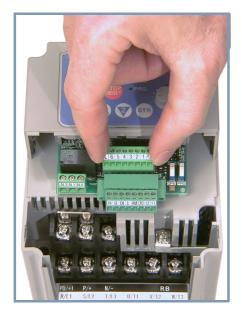


Logic Connector Locations - After removing the front housing cover, take a moment to become familiar with the connectors, as shown below.

Logic Connector Removal/Replacement - The two 8-position main logic connectors are removable from the circuit board to make testing or service more convenient. Note that the relay output connector is not removable, as it must carry higher currents and provide high integrity for alarm conditions. The alarm circuit may carry hazardous live voltages even when the main power to the inverter is OFF. So, never directly touch any terminal or circuit component.

The logic input connector (top connector) can be removed by pulling gently upward as shown (below left). DO NOT force the connector, as damage to the circuit board may occur. Try gently shifting the connector side-to-side while pulling, if having difficulty.

The analog input/output and logic output connector (bottom connector) **has retention screws**. DO NOT attempt to remove the connector before loosening the screws. As the figure shows (below right), use a small Phillips screwdriver to loosen the screw at each end. The connector can be pulled forward easily after the screws are removed.





Orientation to Inverter Features

Power Wiring Access - First, ensure no power source of any kind is connected to the inverter. If power has been connected, wait five minutes after powerdown and verify the Power LED is OFF to proceed. After removing the front housing cover, the housing partition that covers the power wiring exit will be able to slide upward as shown to the right.

Notice the four wire exit slots (on larger model inverters) in the housing partition. This helps keep the power wiring (to the left) separate from signal-level logic or analog wiring (to the right).

Remove the housing partition and as shown as set it aside in a secure place while wiring. Never operate the inverter drive with the partition removed or the front housing cover removed.

The power input and motor 3-phase wiring connect to the lower row of terminals. The upper row of power terminals connect to optional dynamic braking components.

The following sections in this chapter will describe the system design and guide you through a step-by-step installation process. After the section on wiring, this chapter will show how to use the front panel keys to access functions and edit parameters.

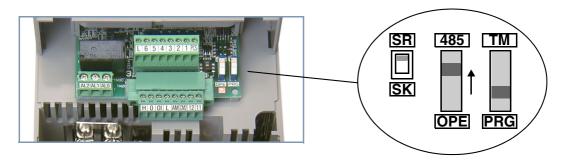




Power and motor connector terminals

OPE / 485 DIP Switch -

The difference between OPE-S and OPE-Smini is the short-circuit inside the connector. If you set 485-side OPE-S,SRW says "----"(communication error) But OPE-Smini works properly.



B

Introduction

This section lists the user-programmable parameters for the SJ200 series inverters and the default values for European and U.S. product types. The right-most column of the tables is blank, so you can record values you have changed from the default. This involves just a few parameters for most applications. This section presents the parameters in a format oriented toward the keypad on the inverter.

Parameter Settings for Keypad Entry

SJ200 series inverters provide many functions and parameters that can be configured by the user. We recommend that you record all parameters that have been edited, in order to help in troubleshooting or recovery from a loss of parameter data.

Inverter model SJ200

MFG. No.

_____}

This information is printed on the specification label located on the right side of the inverter.

Main Profile Parameters

"F" Group Parameters		Default	Setting	User
Func. Code	Name		-FU (USA)	Setting
F001	Output frequency setting	0.0	0.0	
F002	Acceleration (1) time setting	10.0	10.0	
F202	Acceleration (1) time setting, 2nd motor	10.0	10.0	
F003	Deceleration (1) time setting	10.0	10.0	
F203	Deceleration (1) time setting, 2nd motor	10.0	10.0	
F004	Keypad Run key routing	00	00	

Standard Functions

	"A" Group Parameters		Default Setting	
Func. Code	Name	-FEF (EU)	-FU (USA)	User Setting
A001	Frequency source setting	01	00	
A002	Run command source setting	01	02	
A003	Base frequency setting	50.0	60.0	
A203	Base frequency setting, 2nd motor	50.0	60.0	
A004	Maximum frequency setting	50.0	60.0	
A204	Maximum frequency setting, 2nd motor	50.0	60.0	
A005	[AT] selection	00	00	
A011	O–L input active range start frequency	0.0	0.0	
A012	O–L input active range end frequency	0.0	0.0	
A013	O–L input active range start voltage	0.0	0.0	
A014	O–L input active range end voltage	100.	100.	
A015	O–L input start frequency enable	01	01	
A016	External frequency filter time constant	2.	8.	
A020	Multi-speed 0 setting	0.0	0.0	
A220	Multi-speed 0 setting, 2nd motor	0.0	0.0	
A021	Multi-speed 1 setting	0.0	0.0	
A022	Multi-speed 2 setting	0.0	0.0	
A023	Multi-speed 3 setting	0.0	0.0	
A024	Multi-speed 4 setting	0.0	0.0	
A025	Multi-speed 5 setting	0.0	0.0	
A026	Multi-speed 6 setting	0.0	0.0	
A027	Multi-speed 7 setting	0.0	0.0	
A028	Multi-speed 8 setting	0.0	0.0	
A029	Multi-speed 9 setting	0.0	0.0	
A030	Multi-speed 10 setting	0.0	0.0	
A031	Multi-speed 11 setting	0.0	0.0	

-3

C-

	"A" Group Parameters	Default	Setting	User
Func. Code	Name	-FEF (EU)	-FU (USA)	Setting
A032	Multi-speed 12 setting	0.0	0.0	
A033	Multi-speed 13 setting	0.0	0.0	
A034	Multi-speed 14 setting	0.0	0.0	
A035	Multi-speed 15 setting	0.0	0.0	
A038	Jog frequency setting	1.00	1.00	
A039	Jog stop mode	00	00	
A042	Manual torque boost value	5.0	5.0	
A242	Manual torque boost value, 2nd motor	0.0	0.0	
A043	Manual torque boost frequency adjustment	3.0	3.0	
A243	Manual torque boost frequency adjustment, 2nd motor			
A044	V/f characteristic curve selection	02	02	
A244	V/f characteristic curve selection, 2nd motor	02	02	
A045	V/f gain setting	100.	100.	
A046	iSLV voltage compensation gain	100	100	
A246	iSLV voltage compensation gain, 2nd motor	100	100	
A047	iSLV slip compensation gain	100	100	
A247	iSLV slip compensation gain, 2nd motor	100	100	
A051	DC braking enable	00	00	
A052	DC braking frequency setting	0.5	0.5	
A053	DC braking wait time	0.0	0.0	
A054	DC braking force for deceleration	0	0	
A055	DC braking time for deceleration	0.0	0.0	
A056	DC braking / edge or level detec- tion for [DB] input	01	01	
A061	Frequency upper limit setting	0.0	0.0	
A261	Frequency upper limit setting, 2nd motor	0.0	0.0	

	"A" Group Parameters	Default Setting		Lase
Func. Code	Name	-FEF (EU)	-FU (USA)	User Setting
A062	Frequency lower limit setting	0.0	0.0	
A262	Frequency lower limit setting, 2nd motor	0.0	0.0	
A063, A065, A067	Jump (center) frequency setting	0.0	0.0	
A064, A066, A068	Jump (hysteresis) frequency width setting	0.5	0.5	
A071	PID Enable	00	00	
A072	PID proportional gain	1.0	1.0	
A073	PID integral time constant	1.0	1.0	
A074	PID derivative time constant	0.0	0.0	
A075	PV scale conversion	1.00	1.00	
A076	PV source setting	00	00	
A077	Reverse PID action	00	00	
A078	PID output limit	0.0	0.0	
A081	AVR function select	00	00	
A082	AVR voltage select	230/400	230/460	
A092	Acceleration (2) time settin	15.00	15.00	
A292	Acceleration (2) time setting, (2nd motor)	15.00	15.00	
A093	Deceleration (2) time setting	15.00	15.00	
A293	Deceleration (2) time setting, (2nd motor)	15.00	15.00	
A094	Select method to switch to Acc2/ Dec2 profile	00	00	
A294	Select method to switch to Acc2/ Dec2 profile, 2nd motor	00	00	
A095	Acc1 to Acc2 frequency transi- tion point	0.0	0.0	
A295	Acc1 to Acc2 frequency transi- tion point, 2nd motor	0.0	0.0	
A096	Dec1 to Dec2 frequency transi- tion point	0.0	0.0	

	"A" Group Parameters	Defaul	t Setting	User
Func. Code	Name	-FEF (EU)	-FU (USA)	Setting
A296	Dec1 to Dec2 frequency transi- tion point, 2nd motor	0.0	0.0	
A097	Acceleration curve selection	00	00	
A098	Deceleration curve selection	00	00	
A101	101 [OI]–[L] input active range start frequency		0.0	
A102	[OI]–[L] input active range end frequency	0.0	0.0	
A103	[OI]–[L] input active range start current	0.0	0.0	
A104	[OI]–[L] input active range end current	100.	100.	
A105	[OI]–[L] input start frequency enable	01	01	
A141	A input select for calculate function	02	02	
A142	B input select for calculate function	03	03	
A143	A143 Calculation symbol		00	
A145	ADD frequency	0.0	0.0	
A146	ADD direction select	00	00	

Fine Tuning Functions

	"B" Group Parameters Default Setting		Ugon	
Func. Code	Name	-FEF (EU)	-FU (USA)	User Setting
B001	Selection of automatic restart mode	00	00	
B002	Allowable under-voltage power failure time	1.0	1.0	
B003	Retry wait time before motor restart	1.0	1.0	
B004	Instantaneous power failure / under-voltage trip alarm enable	00	00	
B005	Number of restarts on power failure / under-voltage trip events	00	00	
B012	Level of electronic thermal setting	Rated current for each inverter	Rated current for each inverter	
B212	Level of electronic thermal setting, 2nd motor	Rated current for each inverter	Rated current for each inverter	
B013	Electronic thermal characteristic	01	01	
B213	Electronic thermal characteristic, 2nd motor	01	01	
B021	Overload restriction operation mode	01	01	
B022	Overload restriction setting	Rated current x 1.5	Rated current x 1.5	
B023	Deceleration rate at overload restriction	1.0	30.0	
B031	Software lock mode selection	01	01	
B080	[AM] analog signal gain	100.	100.	
B082	Start frequency adjustment	0.5	0.5	
B083	Carrier frequency setting	5.0	5.0	
B084	Initialization mode (parameters or trip history)	00	00	
B085	Country code for initialization	01	02	
B086	Frequency scaling conversion factor	1.0	1.0	

	"B" Group Parameters		Setting	User
Func. Code	Name	-FEF (EU)	-FU (USA)	Setting
B087	STOP key enable	00	00	
B088	Restart mode after FRS	00	00	
B090	Dynamic braking usage ratio	0.0	0.0	
B091	Stop mode selection	00	00	
B092	Cooling fan control	00	00	
B095	Dynamic braking control	00	00	
B096	Dynamic braking activation level	360/720	360/720	
B130	Over-voltage LADSTOP enable	00	00	
B140	Over-current trip suppression	00	00	
B150	Carrier mode	00	00	

Intelligent Terminal Functions

	"C" Group Parameters	Default	Default Setting	
Func. Code	Name	-FEF (EU)	-FU (USA)	User Setting
C001	Terminal [1] function	00	00	
C002	Terminal [2] function	01	01	
C003	Terminal [3] function	02	16	
C004	Terminal [4] function	03	13	
C005	Terminal [5] function	18	09	
C006	Terminal [6] function	09	18	
C011	Terminal [1] active state	00	00	
C012	Terminal [2] active state	00	00	
C013	Terminal [3] active state	00	00	
C014	Terminal [4] active state	00	01	
C015	Terminal [5] active state	00	00	
C016	Terminal [6] active state	00	00	
C021	Terminal [11] function	01	01	
C022	Terminal [12] function	00	00	
C026	Alarm relay terminal function	05	05	
C028	[AM] signal selection	00	00	
C031	Terminal [11] active state	00	00	
C032	Terminal [12] active state	00	00	
C036	Alarm relay active state	01	01	
C041	Overload level setting	Inverter rated current	Inverter rated current	
C042	Frequency arrival setting for acceleration	0.0	0.0	
C043	Arrival frequency setting for deceleration	0.0	0.0	
C044	PID deviation level setting	3.0	3.0	
C052	PID FBV function high limit	100.0	100.0	
C053	PID FBV function low limit	0.0	0.0	
C071	Communication speed selection	06	04	
C072	Node allocation	1.	1.	
C074	Communication parity selection	00	00	

	"C" Group Parameters	Default Setting		User
Func. Code	Name	-FEF (EU)	-FU (USA)	Setting
C075	Communication stop bit selection	1	1	
C076	Communication error select	02	02	
C077	Communication erorr time-out	0.00	0.00	
C078	Communication wait time	0.	0.	
C081	O input span calibration	100.0	100.0	
C082	OI input span calibration	100.0	100.0	
C085	Thermistor input tuning	100.0	100.0	
C086	[AM] terminal offset tuning	0.0	0.0	
C091	Debug mode enable	00	00	
C101	Up/Down memory mode selection	00	00	
C102	Reset selection	00	00	
C141	Input A select for logic output	00	00	
C142	Input B select for logic output	01	01	
C143	Logic function select	00	00	
C144	Terminal [11] ON delay	0.0	0.0	
C145	Terminal [11] OFF delay	0.0	0.0	
C146	Terminal [12] ON delay	0.0	0.0	
C147	Terminal [12] OFF delay	0.0	0.0	
C148	Output relay ON delay	0.0	0.0	
C149	Output relay OFF delay	0.0	0.0	

Motor Constants Functions

	"H" Group Parameters	Default	Setting	User
Func. Code	Name	-FEF (EU)	-FU (USA)	Setting
H003	Motor capacity	Specified by the inverter capacity	Specified by the inverter capacity	
H203	Motor capacity, 2nd setting	Specified by the inverter capacity	Specified by the inverter capacity	
H004	Motor poles setting	4	4	
H204	Motor poles setting, 2nd motor	4	4	
H006	Motor stabilization constant	100	100	
H206	Motor stabilization constant, 2nd motor	100	100	
H007	Motor voltage select	Specified by the inverter voltage	Specified by the inverter voltage	
H207	Motor voltage select, 2nd motor	Specified by the inverter voltage	Specified by the inverter voltage	

Troubleshooting

Safety Messages

Please read the following safety messages before troubleshooting or performing maintenance on the inverter and motor system.



WARNING: Wait at least five (5) minutes after turning OFF the input power supply before performing maintenance or an inspection. Otherwise, there is the danger of electric shock.



WARNING: Make sure that only qualified personnel will perform maintenance, inspection, and part replacement. Before starting to work, remove any metallic objects from your person (wristwatch, bracelet, etc.). Be sure to use tools with insulated handles. Otherwise, there is a danger of electric shock and/or injury to personnel.



WARNING: Never remove connectors by pulling on its wire leads (wires for cooling fan and logic P.C.board). Otherwise, there is a danger of fire due to wire breakage and/or injury to personnel.

General Precautions and Notes

- Always keep the unit clean so that dust or other foreign matter does not enter the inverter.
- Take special care in regard to breaking wires or making connection mistakes.
- Firmly connect terminals and connectors.
- Keep electronic equipment away from moisture and oil. Dust, steel filings and other foreign matter can damage insulation, causing unexpected accidents, so take special care.

Inspection Items

This chapter provides instructions or checklists for these inspection items:

- Daily inspection
- Periodic inspection (approximately once a year)
- Insulation resistance test

Troubleshooting Tips

The table below lists typical symptoms and the corresponding solution(s).

Sympto	m/condition	Probable Cause	Solution
		 Is the frequency command source A001 parameter setting correct? Is the Run command source A002 parameter setting correct? 	 Make sure the parameter setting A001 is correct. Make sure the parameter setting A002 is correct.
		• Is power being supplied to termi- nals [L1], [L2], and [L3/N]? If so, the POWER lamp should be ON.	 Check terminals [L1], [L2], and [L3/N], then [U/T1], [V/T2], and [W/T3]. Turn ON the power supply or check fuses.
	The inverter outputs [U], [V],	• Is there an error code <i>E X X</i> displayed?	• Press the Func. key and determine the error type. Eliminate the error cause, then clear the error (Reset).
The motor will not run.	[W] are not supplying voltage.	 Are the signals to the intelligent input terminals correct? Is the Run Command active? Is the [FW] terminal (or [RV]) connected to [P24] (via switch, etc.) Has the frequency setting for F001 been set greater than zero? Are the control circuit terminals [H], [O], and [L] connected to the potentiometer? Is the RS (reset) function or FRS (free-run stop) function ON? 	 Verify the terminal functions for C001 – C006 are correct. Turn ON Run Command enable. Supply 24V to {FW] or [RV] terminal, if configured. Set the parameter for F001 to a safe, non-zero value. If the potentiometer is the frequency setting source, verify voltage at [O] > 0V. Turn OFF the command(s).
	Inverter outputs [U], [V], [W] are supplying voltage.	• Is the motor load too heavy?	• Reduce load, and test the motor independently.
	The optional remote operator is used (SRW).	• Are the operational settings between the remote operator and the inverter unit correct?	• Check the operator type setting.
The direction of the motor is reversed.		 Are the connections of output terminals [U/T1], [V/T2], and [W/T3] correct? Is the phase sequence of the motor forward or reverse with respect to [U/T1], [V/T2], and [W/T3]? 	 Make connections according to the phase sequence of the motor. In general: FWD = U-V-W, and REV=U-W-V.
		 Are the control terminals [FW] and [RV] wired correctly? Is parameter F004 properly set? 	 Use terminal [FW] for forward, and [RV] for reverse. Set motor direction in F004.

3

6

Troubleshooting

Sympto	m/condition	Probable Cause	Solution
		• If using the analog input, is the current or voltage at [O] or [OI]?	Check the wiring.Check the potentiometer or signal generating device.
the target fre	eed will not reach equency (desired peed).	• Is the load too heavy?	 Reduce the load. Heavy loads activate the overload restriction feature (reduces output as needed).
		• Is the inverter internally limiting the output frequency?	 Check max frequency setting (A004) Check frequency upper limit setting (A061)
		• Is the load fluctuation too great?	• Increase the motor capacity (both inverter and motor).
The rotation	on is unstable.	 Is the supply voltage unstable? Is the problem occurring at a particular frequency?	 Fix power supply problem. Change the output frequency slightly, or use the jump frequency setting to skip the problem frequency.
The RPM of the match the investigation of the frequency setting the setting of th		 Is the maximum frequency setting A004 correct? Does the monitor function D001	 Verify the V/f settings match motor specifications. Make sure all scaling (such
	-	display the expected output frequency?	as A011 to A014) is properly set.
	No downloads	• Was power turned OFF after a parameter edit but before pressing the Store key?	• Edit the data and press the Store key once.
Inverter data is not correct.	have occurred.	• Edits to data are permanently stored at power down. Was the time from power OFF to power ON less than six seconds?	• Wait six seconds or more before turning power OFF after editing data.
	A download to the inverter was attempted.	• Was the power turned OFF within six seconds after the display changed from REMT to INV?	• Copy the data to the inverter again, and keep power ON for six seconds or more after copying.
A parameter will not change after	True for certain parameters	• Is the inverter in Run Mode? Some parameters cannot be edited during Run Mode.	• Put inverter in Stop Mode (press the Stop/reset key). Then edit the parameter.
an edit (reverts to old setting).	True for all parameters	• If you're using the [SFT] intelligent input (software lock function)—is the [SFT] input ON?	• Change the state of the SFT input, and check the B031 parameter (SFT mode).

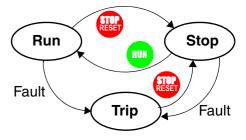
6-

Δ

Monitoring Trip Events, History, & Conditions

Fault Detection and Clearing

The microprocessor in the inverter detects a variety of fault conditions and captures the event, recording it in a history table. The inverter output turns OFF, or "trips" similar to the way a circuit breaker trips due to an over-current condition. Most faults occur when the motor is running (refer to the diagram to the right). However, the inverter could have an internal fault and trip in Stop Mode. In



either case, you can clear the fault by pressing the Stop/Reset key. Additionally, you can clear the inverter's cumulative trip history by performing the procedure "Restoring Factory Default Settings" on page 6–8 (setting B084=00 will clear the trip history but leave inverter settings intact).

Error Codes

An error code will appear on the display automatically when a fault causes the inverter to trip. The following table lists the cause associated with the error.

Error Code	Name	Cause(s)				
E 01	Over current event while at constant speed	The inverter output was short-circuited, or the motor shaft is locked or has a heavy load. These conditions				
E02	Over current event during deceleration	cause excessive current for the inverter, so the inverter output is turned OFF.				
E03	Over current event during acceleration	The dual-voltage motor is wired incorrectly. If b083 is too high, please reduce the value.				
E 0 4	Over current event during other conditions					
<i>E</i> 0 5	Overload protection	When a motor overload is detected by the electronic thermal function, the inverter trips and turns OFF its output.				
E06	Braking resistor overload	When the regenerative braking resistor exceeds the usage time allowance or usage ratio, the inverter trips and turns OFF its output to the motor.				
E07	Over voltage protection	When the DC bus voltage exceeds a threshold, due to regenerative energy from the motor.				
E08	EEPROM error	When the built-in EEPROM memory has problems due to noise or excessive temperature, the inverter trips and turns OFF its output to the motor.				
E09	Under-voltage error	A decrease of internal DC bus voltage below a thresh- old results in a control circuit fault. This condition can also generate excessive motor heat or cause low torque. The inverter trips and turns OFF its output.				

Monitoring Trip Events, History, & Conditions

Error Code	Name	Cause(s)				
E11 E22	CPU error	A malfunction in the built-in CPU has occurred, so the inverter trips and turns OFF its output to the motor.				
E1 2	External trip	A signal on an intelligent input terminal configured a EXT has occurred. The inverter trips and turns OFF the output to the motor.				
E13	USP	When the Unattended Start Protection (USP) is enabled, an error occurred when power is applied while a Run signal is present. The inverter trips and does not go into Run Mode until the error is cleared.				
E14	Ground fault	The inverter is protected by the detection of ground faults between the inverter output and the motor upon during powerup tests. This feature protects the inverter, and does not protect humans.				
E15	Input over-voltage (*)	When the input voltage is higher than the specified value, it is detected 100 seconds after powerup and the inverter trips and turns OFF its output.				
E21	Inverter thermal trip	When the inverter internal temperature is above the threshold, the thermal sensor in the inverter module detects the excessive temperature of the power devices and trips, turning the inverter output OFF.				
E23	Gate array error	An internal inverter error has occurred in communica- tions between the CPU and gate array IC.				
<i>E35</i>	Thermistor	When a thermistor is connected to terminals [6] and [L] and the inverter has sensed the temperature is too high, the inverter trips and turns OFF the output.				
E 6 0	Communications error	The inverter's watchdog timer for the communica- tions network has timed out.				
	Under-voltage (brown- out) with output shutoff	Due to low input voltage, the inverter turns its output OFF and tries to restart. If it fails to restart, then the alarm trips to record the under-voltage error event.				

NOTE: If an EEPROM error (E08) occurs, be sure to confirm the parameter data values are still correct. If the power is turned OFF while the [RS] (Reset) intelligent input terminal is ON, an EEPROM error will occur when power is restored.

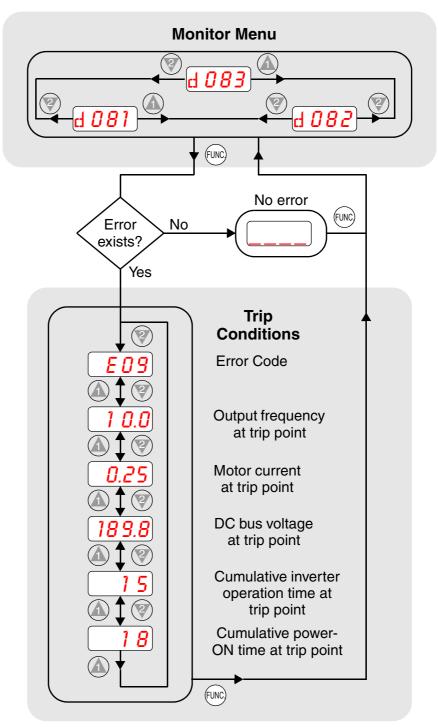
Caution: EXT,PTC trip has a possibility of breaking I/O circuit and breaking EEPROM data *:OVSRC(E15) trip level is relatively changed for 200/400V class in 3440(Core) and 3524(I/O) software.

6

Trip History and Inverter Status

We recommend that you first find the cause of the fault before clearing it. When a fault occurs, the inverter stores important performance data at the moment of the fault. To access the data, use the monitor functions (Dxxx) and select D081 for details about the present fault (E_n). The previous two faults are stored in D082 and D083, with D(E_{n-1} and E_{n-2}). Each error shifts D081–D082 to D082–D083, and writes the new error to D081.

The following Monitor Menu map shows how to access the error codes. When fault(s) exist, you can review their details by first selecting the proper function: D081 is the most recent, and D083 is the oldest.



Restoring Factory Default Settings

You can restore all inverter parameters to the original factory (default) settings for the intended country of use. After initializing the inverter, use the powerup test in Chapter 2 to get the motor running again. To initialize the inverter, follow the steps below.

No.	Action	Display	Func./Parameter					
1	Use the $FUNC$, (\textcircled{A}) , and (\textcircled{V}) keys to navigate to the "B" Group.	b	"B" Group selected					
2	Press the FUNC key.	b <i>001</i>	First "B" parameter selected					
3	Press and hold the 🕼 key until ->	b <i>085</i>	Country code for initialization selected					
4	Press the FUNC key.	60	00 = Japan, 01 = Europe, 02 = U.S.					
5	Confirm the country code is correct. Do not change it unless you are absolutely sure the power input voltage range and frequency match the country code setting. To change the country code, press (A) or (?) to set, (STR) to store.							
6	Press the FUNC key.	b 085	Country code for initialization selected					
7	Press the 😵 key.	ь <i>084</i>	Initialization function selected					
8	Press the FUNC key.		00 = initialization disabled, clear trip history only					
9	Press the 🕼 key.	01	01 = initialization enabled					
10	Press the STR key.	ь <i>084</i>)	Initialization now enabled to restore all defaults					
11	Press and hold the (UNC), (A), and (V) keys. Do not release yet.	ь <i>084</i>)	First part of special key sequence					
12	Holding the keys above, press and hold the (STOP) key for 3 sec.	b <i>084</i>)	Final part of special key sequence					
13	Release only the	d 001	Initialization begins when display starts blinking					
14	Now release the FUNC, (Δ) , and (∇) keys only after the d001 display function begins blinking.	EU USR	Default parameter country code shown during initialization process (left-most char displays alternating pattern)					
15	Initialization is complete.	d 001	Function code for output frequency monitor shown					



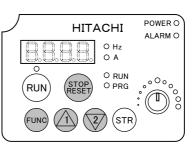
NOTE: Initialization cannot be performed with a remote operator panel. Disconnect the device and use the inverter's front panel keypad.

EEPROM Compulsory Initialization

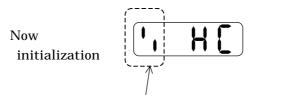
All of EEPROM data are stored default setting

-method-

- 1. After setting C091=01, store '**FF' at EEPROM address 11d4(C092 setting).
- 2. Then press and hold the FUNC, UP, and DOWN key.



- 3. After that press RESET key and release.
- 4. Then INV starts compulsory initialization as it displays like below.



At the left side the bars blink and roll

- 5. EEPROM compulsory initialization completes.
- 6. Set Voltage-class (C197), and set C195, b085(both must be the same.)
- 7. Set INV kW Code (C196) the wrong value once intentionally and store, then set the right value. After that start initialization with b084

-C081,C082-

O-L adjustment at factory(not C81, not C82) JPN version is 1 byte definition Core:up to 3388(or before) IO:up to 3433(or before)

EU/USA version is 2 byte definition from the beginning. Core: 3440 or after IO: 3441 or after

When initialization of b084 or copying C081 and C082 are set different value, so need to set again.

ERROR Check

error	description			
No display	DC bus charged			
	IO board connection & cable connection			
	OPE connection			
	short bar P1- PD			
	Cooling FAN failure			
	Connection between IO board & OPE(L200)			
E08/E11	EEPROM recovery(initialization C92 display 11d4=ff)			
E22	IO board connection & cable connection(communication error			
	between ISPM & IO board)			
	INV type code is wrong SJ200 & L200			
	EEPROM recovery(initilalization C92 display			
	11d4=ff)(because MCU can't read EEPROM)			
8888 display	EEPROM data changed. check C194			
OC trip/E23/	Disconnect motor wire and check output voltage			
E30/E14				
	Core(ISPM) failure(not repairable)			
(Power Off				
display)				
E09 with	maybe thyristor off, please check waveform of DC bus voltage.			
motor				
E12(EXT)	check C01-C06 (EXT=12)			
E35(PTC)	check C06(SJ200)-C05(L200)(PTC=19) ,check C85 value			
E05(Over Load),OC	check b32 value			
trip(L200)is prematured				
Cooling FAN doesn't	check b92			
work				
INV doesn't work	check DIP switch on ISPM(Power Module pcb)			
MOV failure, or you got	check d109 display after C91 set 01			
returned INV				
bar-bar-bar	Set dip Switch from 485 to PRG			
display(OPE-S,OPE-SRE,				
not OPE-Smini)				
or				
R-ERROR				
COMM.<1>(SRW)				
No display	check the bar of P-line.			

Debug Mode

If you set debug mode enable (C091 =01), the function below will be available. When debugging, you can use only standard OPE (cannot use SRW) Make sure of returning C091=00 after debugging.

There are some monitor or function-code for testing and maintenance which is not released for users.

The content of each function follows below.

Monitor mode

No	Function name	Code	Run Mode Edit	Range	Description	Res.	defa ult	unit
1	Control-frequenc y monitor	d101	-	0. 0 ~ 400. 0	Monitors control frequency	0. 1[Hz]	-	Hz
2	DC voltage monitor	d102	-	0. 0 ~ 999. 9	Monitors the P-N voltage	0. 1[V]	-	v
3	BRD ON time monitor	d103	-	0. 0 ~ 100. 0	Monitors the time during BRD ON	0. 1[sec]	-	%
4	Electric thermal monitor	d104	-	0. 0 ~ 100. 0	Monitors integration of the current when exceeding the thermal level.	0.1%	-	-
5	Core MCU NO.	d106	-	0000~99999	Monitors the version of the core program	1	-	-
6	IO MCU NO.	d107	-	0000~99999	Monitors the version of the IO program	1	-	-
7	Peak voltage monitor	d109	-	0. 0 ~ 999. 9	Monitors the peak P-N voltage	0. 1[V]	-	v

Function mode

No	Function name	Code	Run Mode Edit	Range	Description	Res.	defa ult	unit
8	Debug mode enable	C091	OK	00(disable)/ 01(enable)	Debug mode select	-	00	-
9	Debug mode data set	C092	OK	0000~FFFF	Hexadecimal display (Do not set)	-	1200	-
10	Debug mode data monitor	C093	ОК	0000~FFFF	Hexadecimal display (Do not set)	-	1200	-
11	Debug mode bit control	C094	OK	Address set range 0000 - FFFF-> 0-7 bit select	Hexadecimal display (Do not set)	-	1200	-
12	Debug mode select	C095	OK	00(Core)/01(IO)	Doesn't store to EEPROM	-	00	-
13	O input span calibration for function test	C121	-	0000~FFFF	Hexadecimal display (Do not set)	-	3E8	-
14	OI input span calibration for function test	C122	-	0000~FFFF	Hexadecimal display (Do not set)	-	3E8	-
15	OI Zero calibration for function test	C123	-	0~65535	(Do not set)	-	200	-
16	Area code select	C195	-	00(JPN)/01(EU) /02(USA)	Area code select	-	-	-
17	kW code	C196	-	0.2~7.5	Capacity select	-	-	-
18	Voltage-class select	C197	-	00(200V)/01(400V)	Voltage-class select	-	-	-

Maintenance and Inspection

Monthly and Yearly Inspection Chart

Item Inspected			Inspection Cycle		Inspection		
		Check for	Month	Year	Method	Criteria	
	Ambient environment	Extreme temperatures & humidity	~		Thermometer, hygrometer	Ambient temperature between -10 to 40°C, non-condensing	
Overall	Major devices	Abnormal noise & vib.	~		Visual and aural	Stable environment for electronic controls	
	Power supply voltage	Voltage tolerance	7		Digital volt meter, measure between inverter terminals [L1], [L2], [L3]	200V class: 200 to 240V 50/60 Hz 400V class: 380 to 460V 50/60 Hz	
	Ground Insulation	Adequate resistance		~	Digital volt meter, GND to terminals	5 Meg. Ohms or greater	
	Mounting	No loose screws		~	Torque wrench	M3: 0.5 – 0.6 Nm M4: 0.98 – 1.3 Nm M5: 1.5 – 2.0 Nm	
	Components	Overheating		~	Thermal trip events	No trip events	
	Housing	Dirt, dust		~	Visual	Vacuum dust and dirt	
Main	Terminal block	Secure connections		~	Visual	No abnormalities	
circuit	Smoothing capacitor	Leaking, swelling	1		Visual	No abnormalities	
	Relay(s)	Chattering		~	Aural	Single click when switching ON or OFF	
	Resistors	Cracks or discoloring		~	Visual	Use Ohm meter to check braking resistors	
	Cooling fan	Noise	~	Power down, manually rotate		Rotation must be smooth	
		Dust	~		Visual	Vacuum to clean	
Control circuit	Overall	No odor, discoloring, corrosion		~	Visual	No abnormalities	
	Capacitor	No leaks or deformation	~		Visual	Undistorted appearance	
Display	LEDs	Legibility	~		Visual	All LED segments work	

Note 1: The life of a capacitor is affected by the ambient temperature. See "Capacitor Life Curve" on page 6–11.

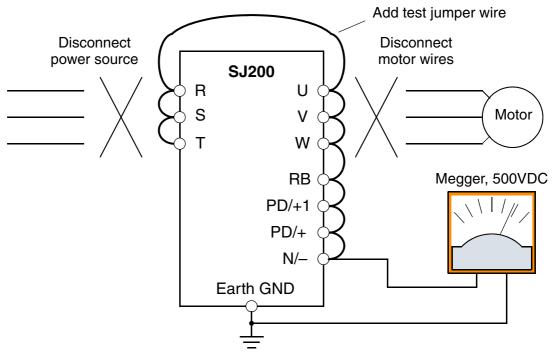
Note 2: The inverter must be cleaned periodically. If dust accumulates on the fan and heat sink, it can cause overheating of the inverter.

Megger Test

The *megger* is a piece of test equipment that uses a high voltage to determine if an insulation degradation has occurred. For inverters, it is important that the power terminals be isolated from the Earth GND terminal via the proper amount of insulation.

The circuit diagram below shows the inverter wiring for performing the megger test. Just follow the steps to perform the test:

- 1. Remove power from the inverter and wait at least 5 minutes before proceeding.
- 2. Open the front housing panel to access the power wiring.
- **3.** Remove all wires to terminals [R, S, T, RB, PD/+1, PD/+, N/–, U, V, and W]. Most importantly, the input power and motor wires will be disconnected from the inverter.
- **4.** Use a bare wire and short terminals [R, S, T, RB, PD/+1, PD/+, N/–, U, V, and W] together as shown in the diagram.
- 5. Connect the megger to the inverter Earth GND and to the shorted power terminals as shown. Then perform the megger test at 500 VDC and verify $5M\Omega$ or greater resistance.



- 6. After completing the test, disconnect the megger from the inverter.
- 7. Reconnect the original wires to terminals [R, S, T, RB, PD/+1, PD/+, N/–, U, V, and W].



CAUTION: Do not connect the megger to any control circuit terminals such as intelligent I/O, analog terminals, etc. Doing so could cause damage to the inverter.

CAUTION: Never test the withstand voltage (HIPOT) on the inverter. The inverter has a surge protector between the main circuit terminals above and the chassis ground.

6

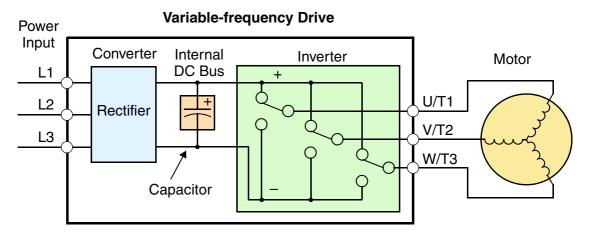
Spare parts

We recommend that you stock spare parts to reduce down time, including these parts:

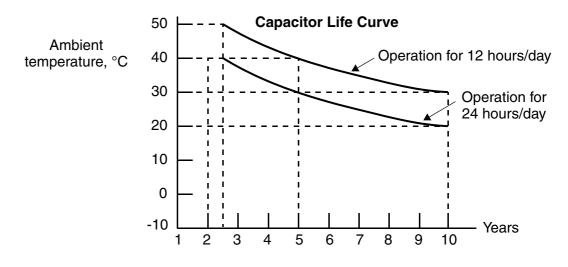
Part description	Symbol	Quar	ntity	Notes	
Tart description	Symbol	Used	Spare	ivotes	
Cooling fan	FAN	1	1	015NF, 022NF, 030LF, 015HF to 075HF	
Case	CV	1	1	 Front case Key cover Case Bottom cover 	

Capacitor Life Curve

The DC bus inside the inverter uses a large capacitor as shown in the diagram below. The capacitor handles high voltage and current as it smooths the power for use by the inverter. So, any degradation of the capacitor will affect the performance of the inverter.



Capacitor life is reduced in higher ambient temperatures, as the graph below demonstrates. Be sure to keep the ambient temperature at acceptable levels, and perform maintenance inspections on the fan, heat sink, and other components. If the inverter is installed on a cabinet, the ambient temperature is the temperature inside the cabinet.



General Inverter Electrical Measurements

The following table specifies how to measure key system electrical parameters. The diagrams on the next page show inverter-motor systems and the location of measurement points for these parameters.

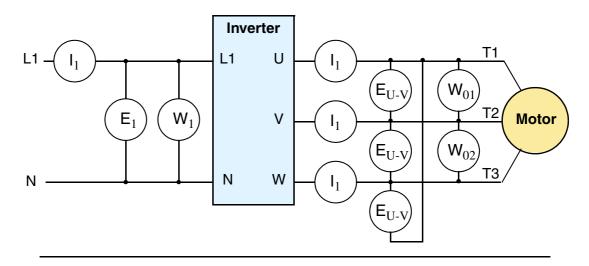
Parameter	Circuit location of measurement	Measuring instrument Notes		Reference Value	
Supply voltage E ₁	E_R – across L1 and L2 E_S – across L2 and L3 E_T – across L3 and L1	Moving-coil type voltmeter or rectifier type voltmeter		Commercial supply voltage (200V class) 200– 240V, 50/60 Hz 400V class 380– 460V, 50/60 Hz	
Supply current I ₁	$I_r - L1, I_s - L2, I_t - L3$		Total effective value		
Supply power W ₁	W_{11} – across L1 and L2 W_{12} – across L2 and L3		Total effective value	—	
Supply power factor Pf ₁	$Pf_1 = \frac{1}{\sqrt{3}}$	_			
Output voltage E ₀	E_U – across U and V E_V – across V and W E_W – across W and U	Rectifier type voltmeter	Total effective value		
Output current I _o	$\begin{split} & I_U - U \\ & I_V - V \\ & I_W - W \end{split}$	Moving-coil ammeter	Total effective value		
Output power W _o	W_{01} – across U and V W_{02} – across V and W	Electronic type wattmeter	Total effective value		
Output power factor Pf _o	Calculate the output power output current I, and output $Pf_0 = \frac{1}{\sqrt{3}}$				

- **Note 1:** Use a meter indicating a fundamental wave effective value for voltage, and meters indicating total effective values for current and power.
- **Note 2:** The inverter output has a distorted waveform, and low frequencies may cause erroneous readings. However, the measuring instruments and methods listed above provide comparably accurate results.
- **Note 3:** A general-purpose digital volt meter (DVM) is not usually suitable to measure a distorted waveform (not pure sinusoid).

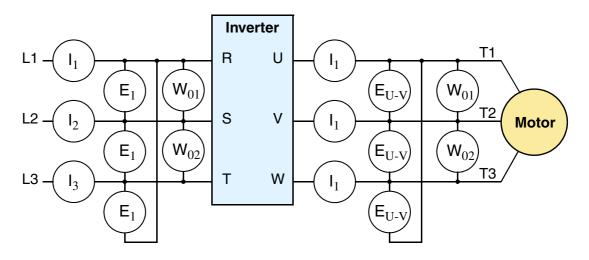
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The figures below show measurement locations for voltage, current, and power measurements listed in the table on the previous page. The voltage to be measured is the fundamental wave effective voltage. The power to be measured is the total effective power.

Single-phase Measurement Diagram



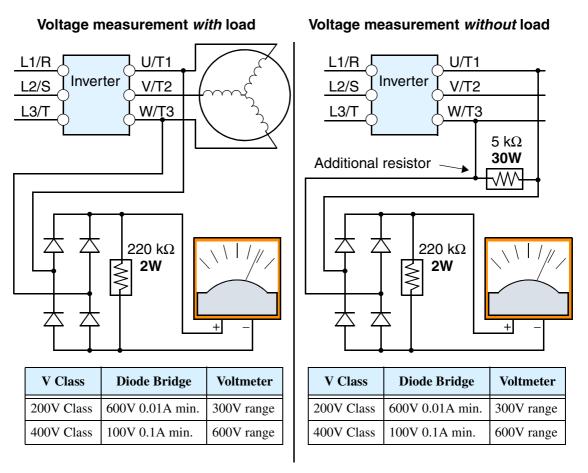
Three-phase Measurement Diagram



R

Inverter Output Voltage Measurement Techniques

Taking voltage measurements around drives equipment requires the right equipment and a safe approach. You are working with high voltages and high-frequency switching waveforms that are not pure sinusoids. Digital voltmeters will not usually produce reliable readings for these waveforms. And, it is usually risky to connect high voltage signals to oscilloscopes. The inverter output semiconductors have some leakage, and no-load measurements produce misleading results. So, we highly recommend using the following circuits to measure voltage for performing the equipment inspections.





HIGH VOLTAGE: Be careful not to touch wiring or connector terminals when working with the inverters and taking measurements. Be sure to place the measurement circuitry components above in an insulated housing before using them.

6

IGBT Test Method

The following procedure will check the inverter transistors (IGBTs) and diodes:

- 1. Disconnect input power to terminals [R, S, and T] and motor terminals [U, V, and W].
- 2. Disconnect any wires from terminals [+] and [RB] for regenerative braking.
- **3.** Use a Digital Volt Meter (DVM) and set it for 1Ω resistance range. You can check the status of the charging state of terminals [R, S, T, U, V, W, RB, +, and –] of the inverter and the probe of the DVM by measuring the charging state.

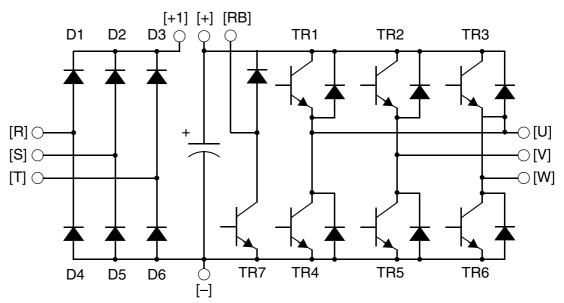


Table Legend – Almost infinite resistance: $\cong \infty \Omega$ Almost zero resistance: $\cong 0 \Omega$

Part	DVM Measured		Part	DVM		Measured	Measured Part	DVM		Measured	
rart	+	Ι	Value	rart	+	I	Value	ran	+	Ι	Value
D1	[R]	+1	$\cong \infty \Omega$	D5	[S]	[N]	$\cong 0 \ \Omega$	TR4	[U]	[–]	$\cong 0 \ \Omega$
	+1	[R]	$\cong 0 \ \Omega$		[N]	[S]	$\cong \infty \Omega$		[-]	[U]	$\cong { { \ o } } \Omega$
D2	[S]	+1	$\cong \infty \Omega$	D6	[T]	[N]	$\cong 0 \ \Omega$	TR5	[V]	[–]	$\cong 0 \ \Omega$
	+1	[S]	$\cong 0 \ \Omega$		[N]	[T]	$\cong \infty \Omega$		[–]	[V]	$\cong \infty \Omega$
D3	[T]	+1	$\cong \infty \Omega$	TR1	[U]	[+]	$\cong \infty \Omega$	TR6	[W]	[–]	$\cong 0 \ \Omega$
	+1	[T]	$\cong 0 \ \Omega$		[+]	[U]	$\cong 0 \ \Omega$		[-]	[W]	$\cong \infty \Omega$
D4	[R]	[N]	$\cong 0 \ \Omega$	TR2	[V]	[+]	$\cong \infty \Omega$	TR7	[RB]	[+]	$\cong 0 \ \Omega$
	[N]	[R]	$\cong \infty \Omega$		[+]	[V]	$\cong 0 \ \Omega$		[+]	[RB]	$\cong \infty \Omega$
				TR3	[W]	[+]	$\cong \infty \Omega$		[RB]	[–]	$\cong 0 \ \Omega$
					[+]	[W]	$\cong 0 \ \Omega$		[-]	[RB]	$\cong 0 \ \Omega$



NOTE: The resistance values for the diodes or the transistors will not be exactly the same, but they will be close. If you find a significance difference, a problem may exist.



NOTE: Before measuring the voltage between [+] and [–] with the DC current range, confirm that the smoothing capacitor is discharged fully, then execute the tests.

Replacing the fan

The following series inverter is equipped a cooling fan.

(200V class): 1,5kW, 2.2kW, 3.7kW

(400V class): 1,5kW, 2.2kW, 3.7kW

A way to replace the fan follows below.

By the way, primary released product is different from not primary (secondly -) one about the way to remove the fan. In the case of replacing the fan, please remove the housing cover first, and then replace the new fan. Please refer to section 4.6 about the way to remove the housing cover.

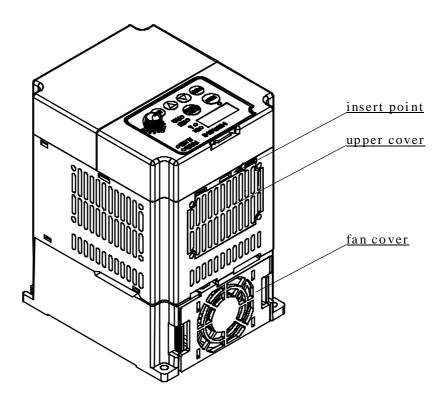
Please make sure of the specification label to discriminate whether it's primary released product or not.

REV.NO.: A	- primary released products
REV.NO.: not A	- not primary (secondly -) released products

1.Insert the minus screw driver etc to the insert point, and remove the upper cover.

2.Remove the connector (CN4) of the fan.

3.Remove the fan cover and replace new one.



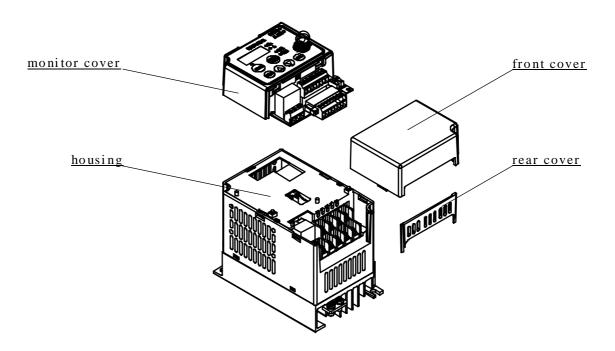
Removing the housing cover

There are several ways which depend on the scale of the housing cover. scale (small): $(200V \text{ class}) \quad 0.2kW, 0.4kW, 0.75kW$ scale (middle): $(200V \text{ class}) \quad 1.5kW, 2.2kW, 3.7kW$ $(400V \text{ class}) \quad 0.4kW - 3.7kW$

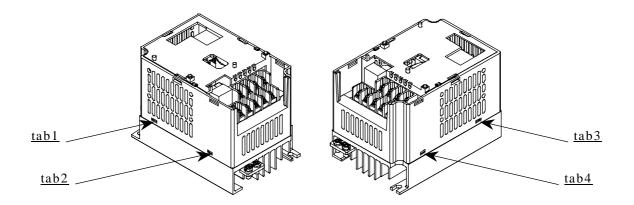
Scale (small)

1.Remove the monitor cover, front cover and rear cover.

When removing the monitor cover, please remove the communication cable from the front cover side.



2.Insert the minus screw driver between the cooling fin and the housing, and unlock the tabs (4 points at the left and right side).

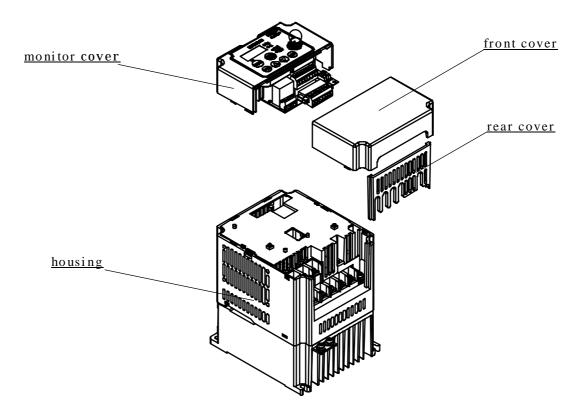


3. Remove the housing.

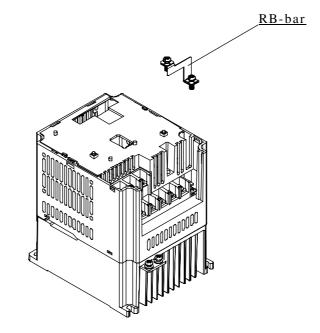
Scale (middle)

1.Remove the monitor cover, front cover and rear cover.

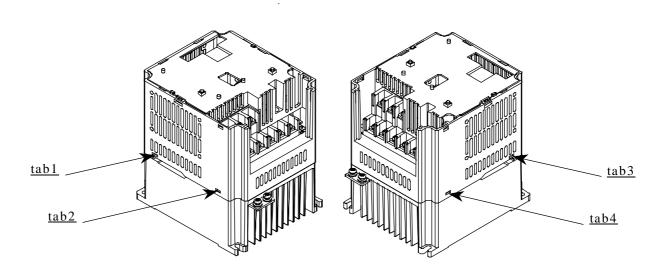
When removing the monitor cover, please remove the communication cable from the front cover side.



2.Remove the RB-bar.



3.Insert the minus screw driver between the cooling fin and the housing, and unlock the tabs (4 points at the left and right side.

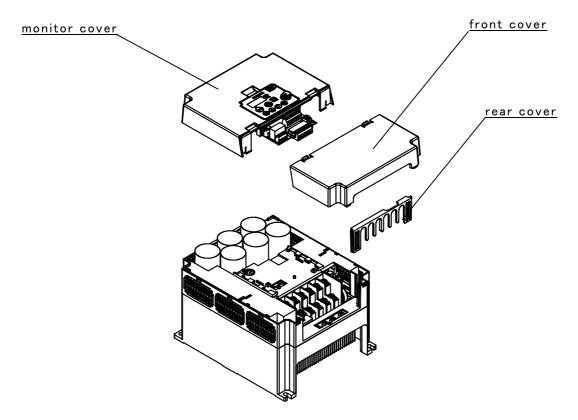


4. Remove the housing.

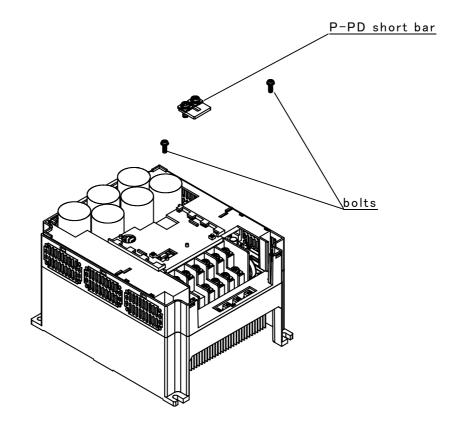
Scale (large)

① Remove the monitor cover, front cover and rear cover.

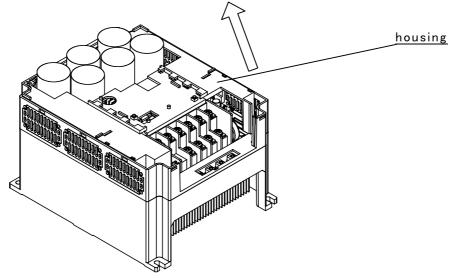
When removing the monitor cover, please remove the communication cable from the front cover side.

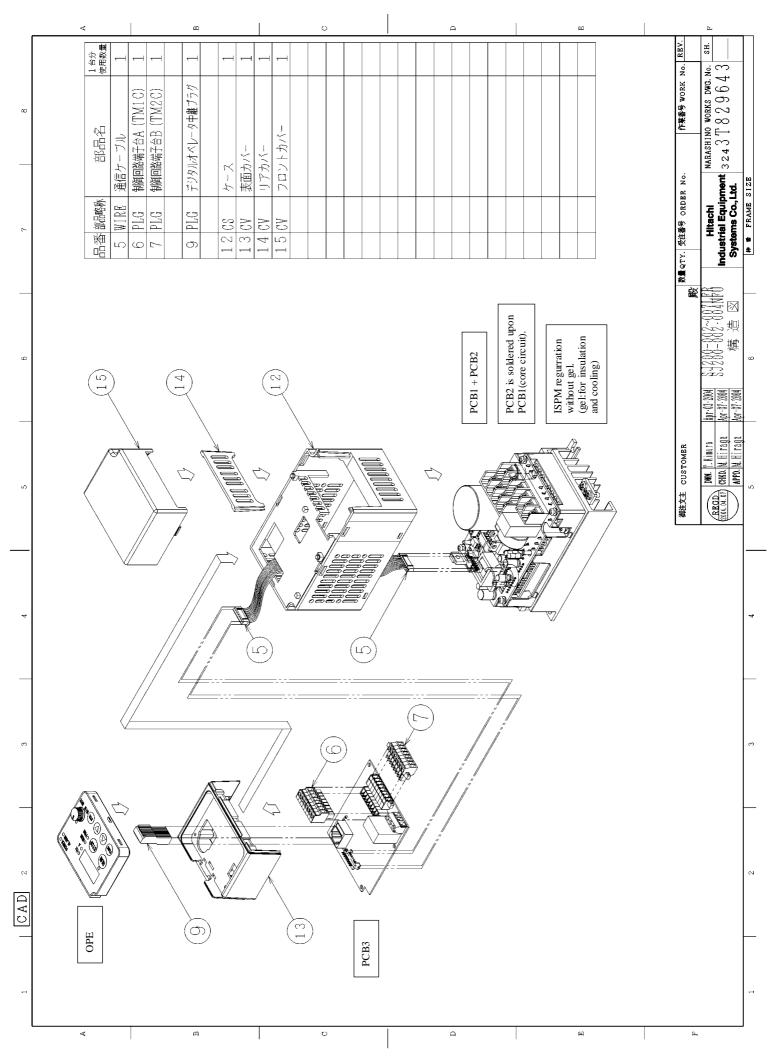


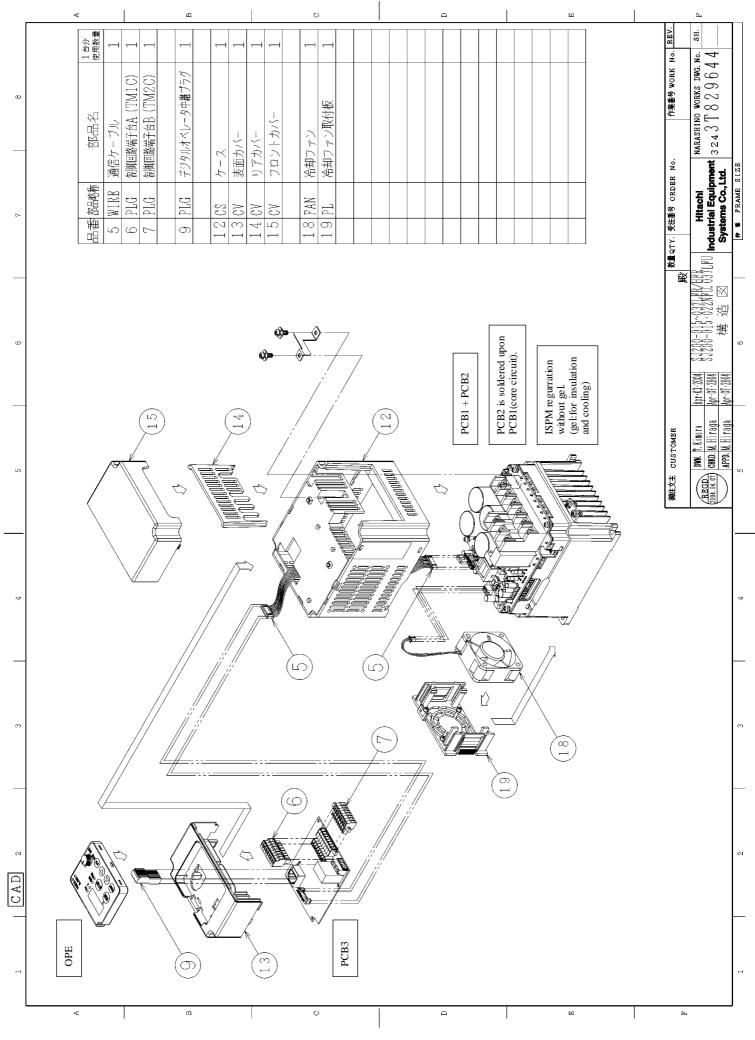
2 Remove the two bolts and P-PD short bar.

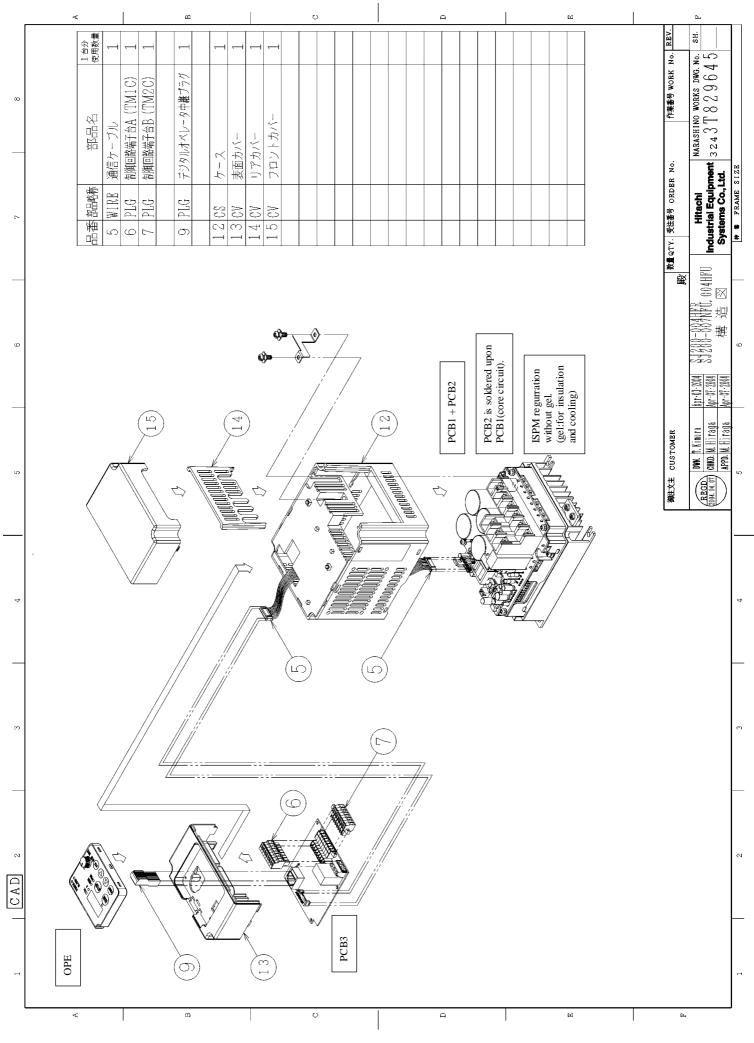


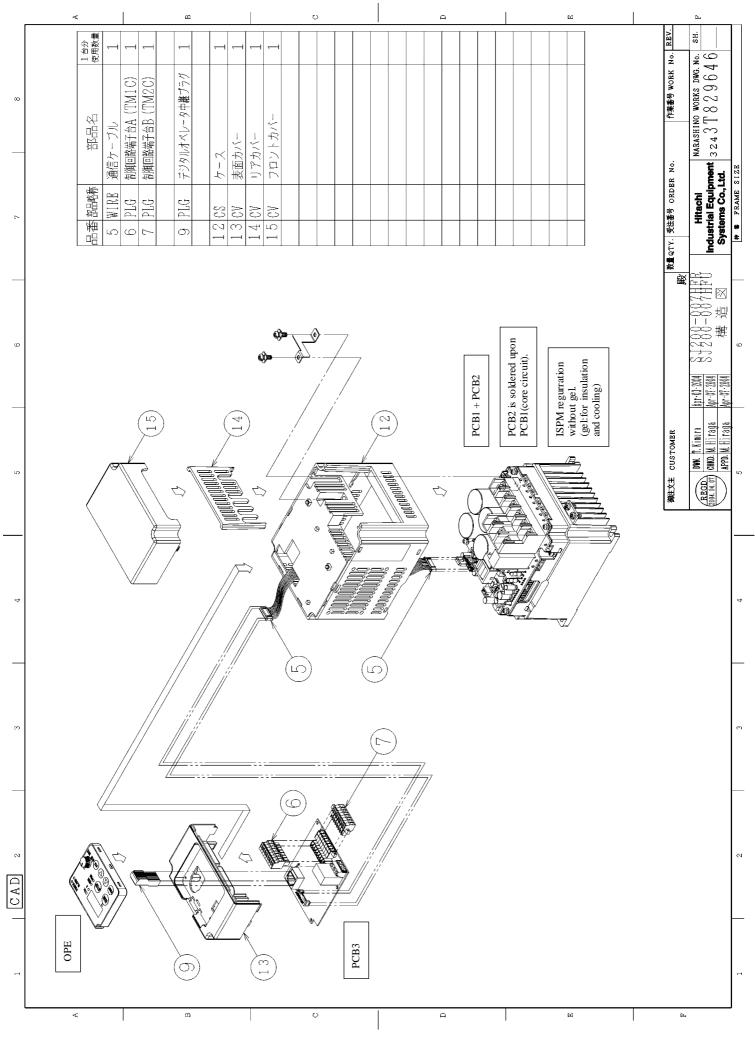
3 Remove the housing



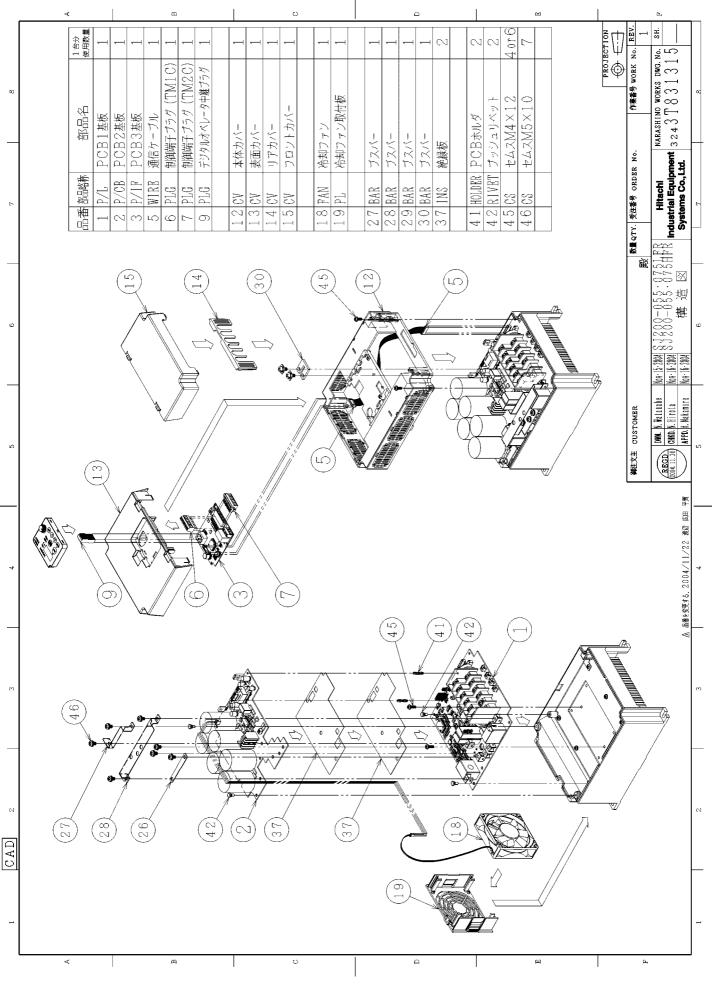




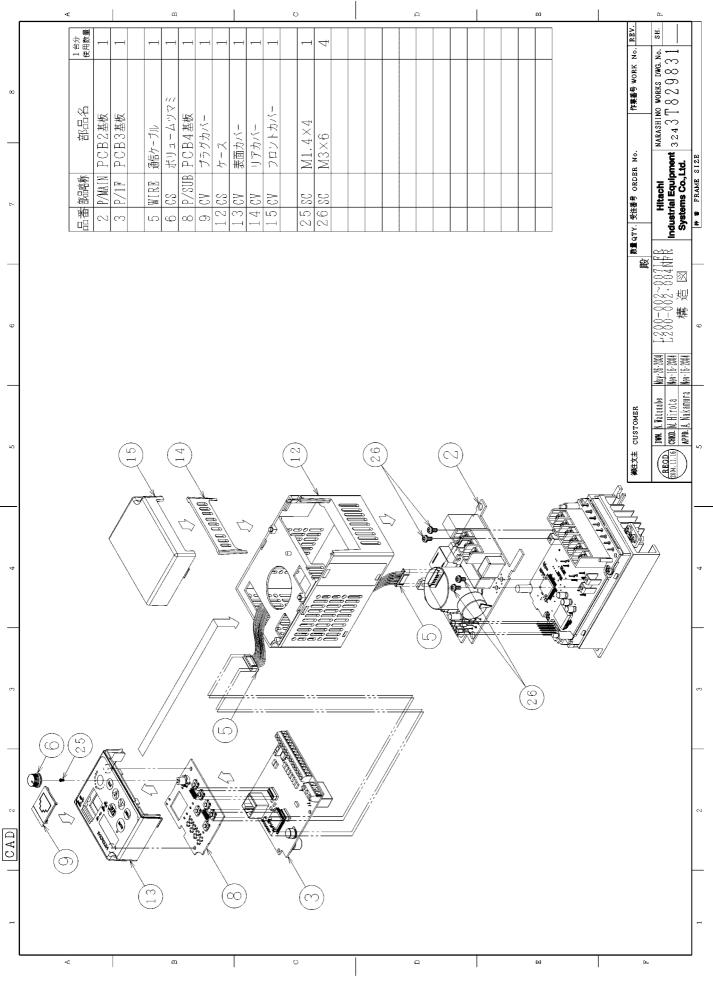


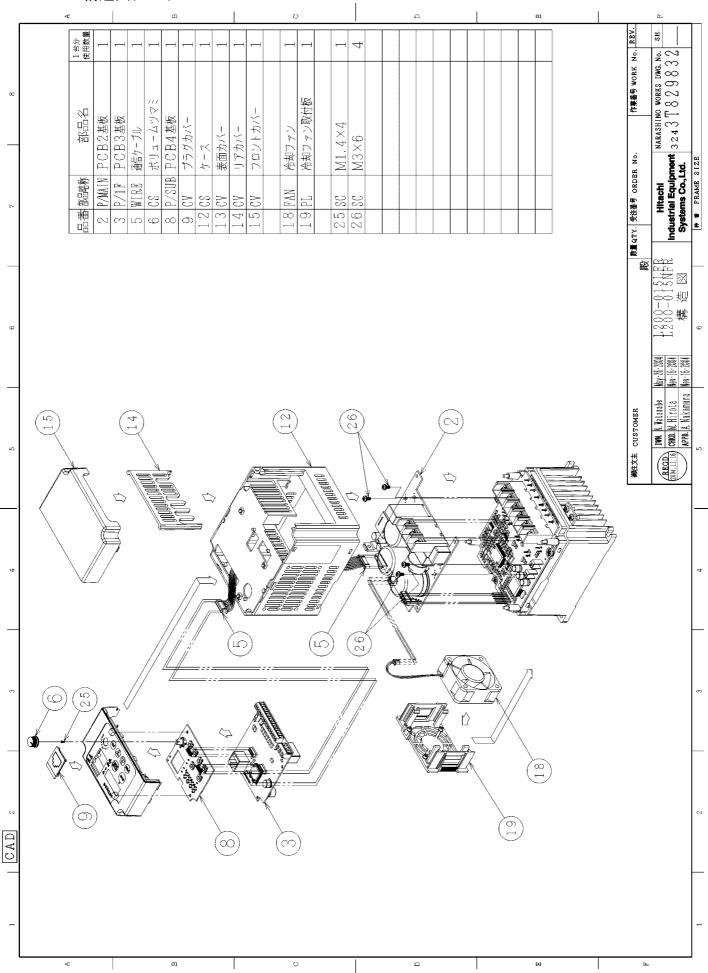


5.1.構造図(5/11)



5.1.構造図(6/11)

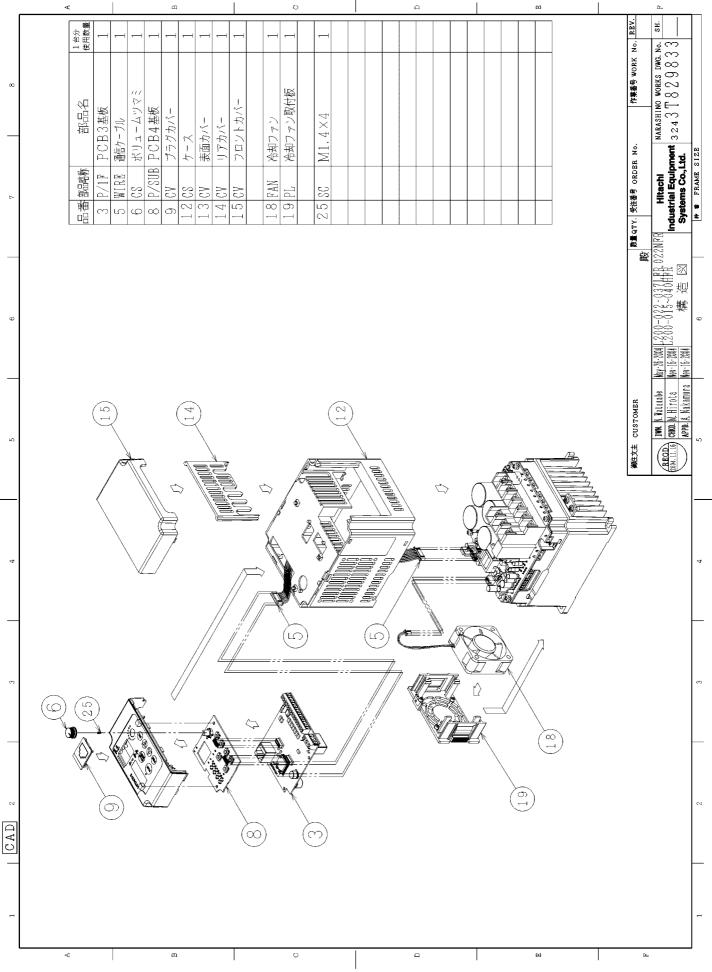


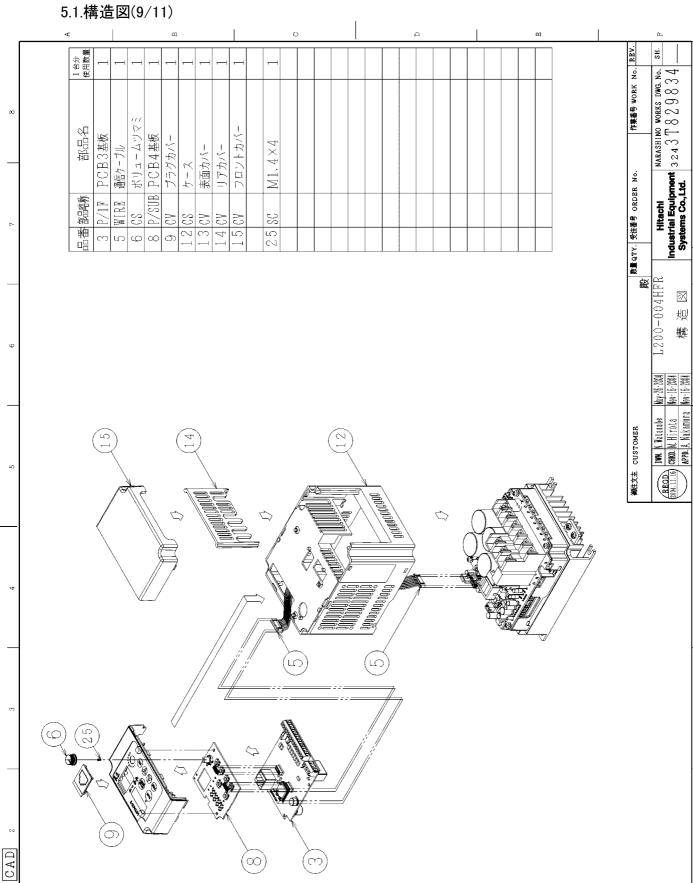


5-7

5.1.構造図(7/11)







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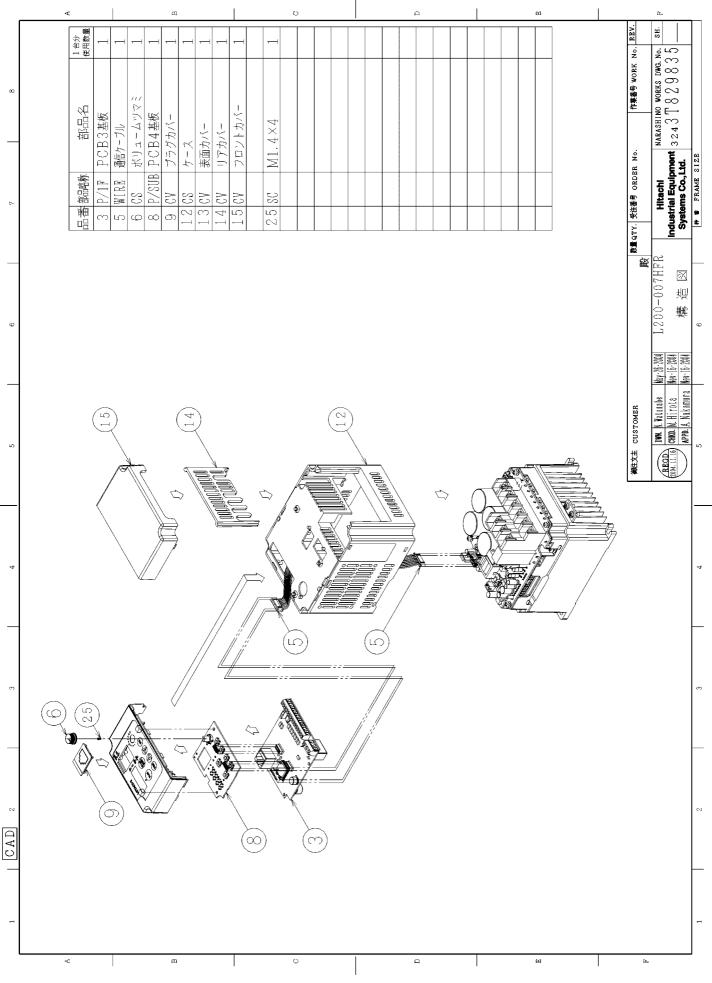
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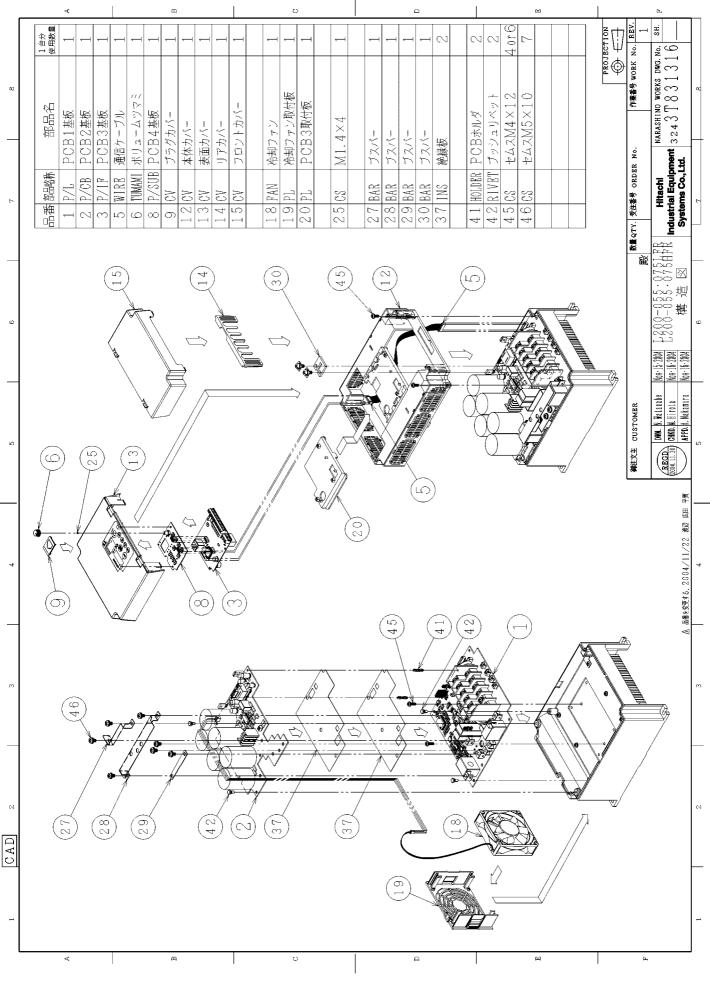
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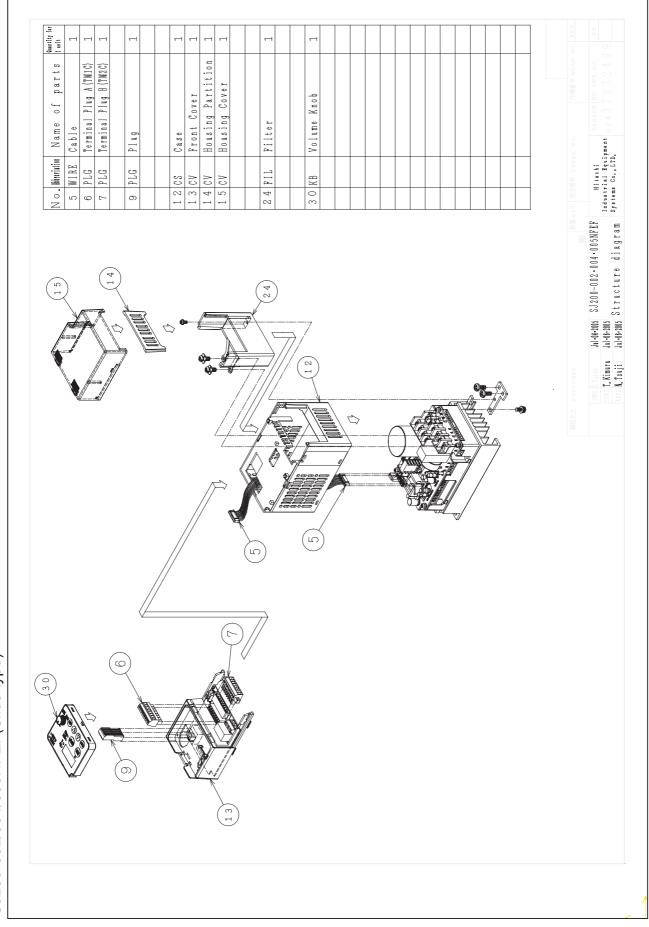
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5.1.構造図(10/11)

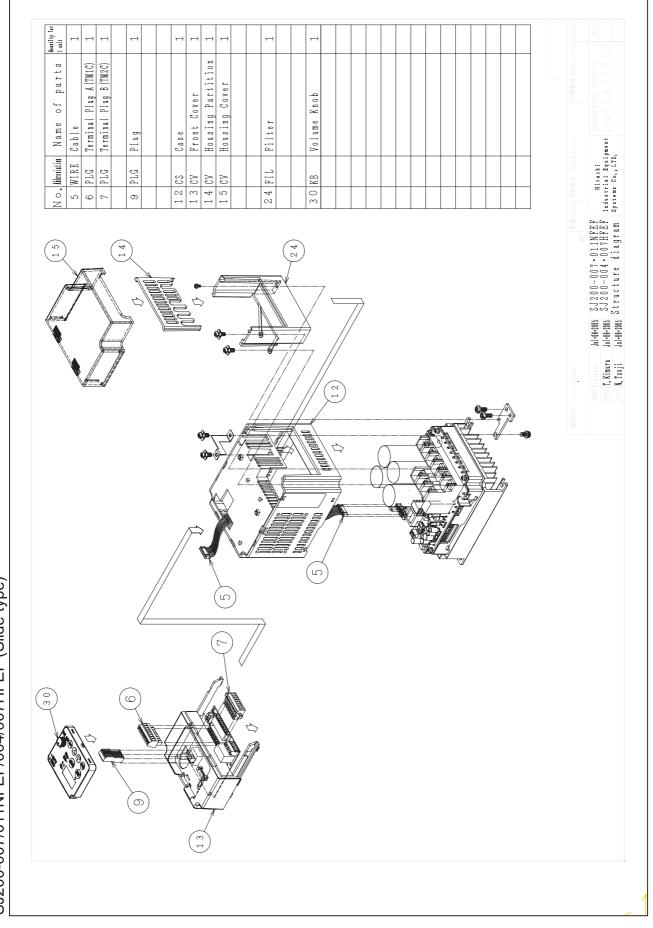


5.1.構造図(11/11)

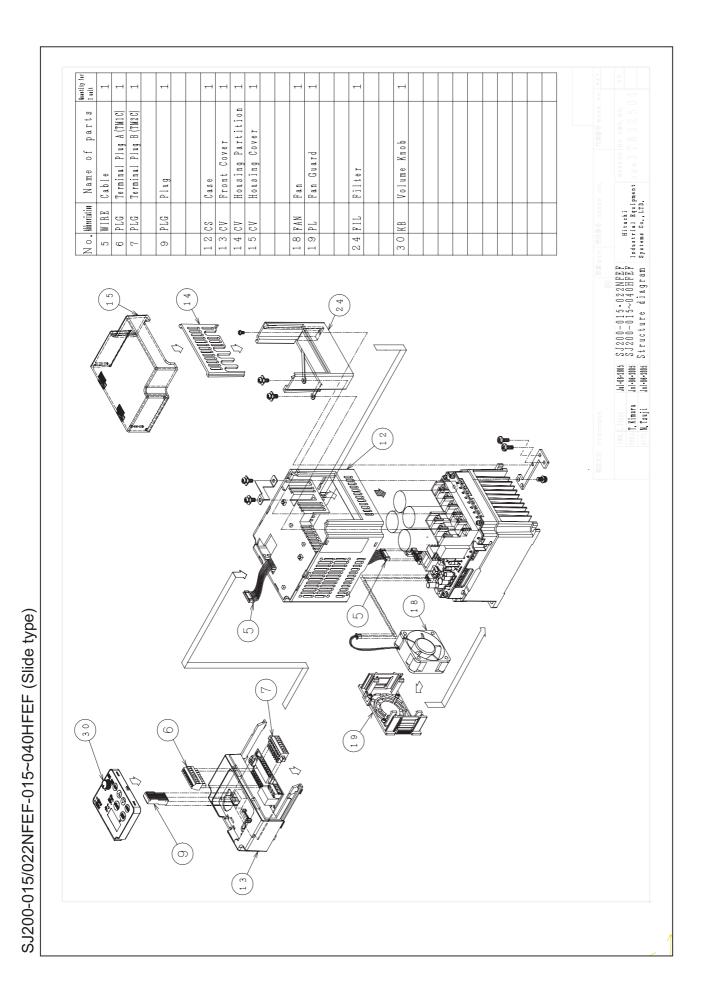


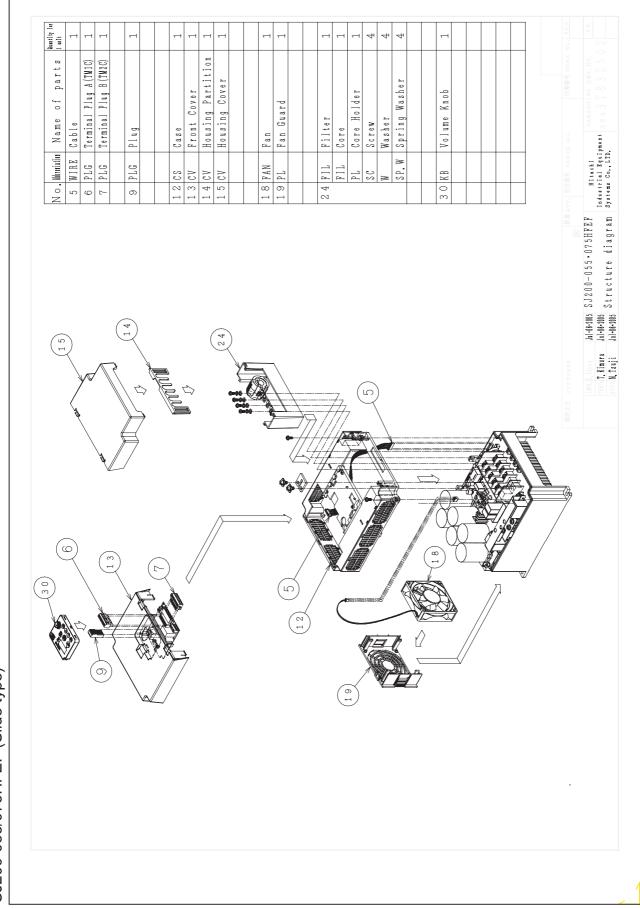


SJ200-002/004/005NFEF(Slide type)



SJ200-007/011NFEF/004/007HFEF (Slide type)





SJ200-055/075HFEF (Slide type)

